

# **ASSEMBLY INSTRUCTIONS** STANDARD MIXING/BELT DRIVE

www.vigorpilot.com



### **VIGOR SPECIFICATIONS**

Overall Length Overall Height

55.25"

18."

680 - 710mm\*

Main Rotor Blade Length (Main rotor blades not included) Tail Rotor Diameter

Gear Ratio

Gross Weight

10.34"

9.33:1:5.18

10.5 lbs.





#### INTRODUCTION

#### The Wait is over!

Congratulations on your purchase of the new JR Vigor helicopter kit. The Vigor, designed by 2-time World Champion, and 11-time US Nationals Champion Curtis Youngblood, in conjunction with IR engineers, has been in development for nearly 3 years and thousands of test flights, to bring you a model that sets the new standard for others to be judged.

#### Designed By a Champion To Be a Champion

The Vigor was designed by Curtis with rigidity, durability, and simplicity in mind, The Vigor's unique main frame design utilizes two straight frame plates and achieves its unmatched strength and rigidity through the use of internal "P" beam supports, rather than the engine. This results in a very simple, yet highly rigid, frame that eliminates any unwanted loads from being applied to the engine during flight.

In addition to the Vigor's unique frame, the cooling system has also been completely redesigned from the ground up by Curtis through countless hours of engine cooling fan efficiency testing. The end result is a cooling system that provides double the airflow of a conventional cooling system, with no increase in power consumption. This system will allow the engine to run more consistently, and at a more consistent temperature.

#### **Building From a Proven Performer**

As you will see when you begin to assemble your Vigor, many of the rotor head and tail rotor components are similar to the JR Ergo 60 components, but with many enhancements.

The Vigor's pre-assembled main rotor head has been completely redesigned from the ground up to provide increased stability and improved flight characteristics, while retaining a reliable and easy-to-maintain system.

#### Low Parts Count Means Quick Assembly

You will find that your Vigor will assemble very quickly due to its well-thoughtout/straight-forward design, low parts count, and pre-assembled main rotor head, washout unit, and tail pitch slider assemblies. The building time for the Vigor usually takes only 10-12 hours from start to finish.

#### Team Tips

Throughout the sections of this instruction manual, you will find dozens of "Team Tips." These tips have been provided by Team JR's Curtis Youngblood and Len Sabato to guide you through the assembly of your Vigor with helpful tips and suggestions that will help you get the most from your new JR Vigor from the very start.

#### www.vigorpilet.com

For the latest, up-to-date information on the Vigor, visit the Vigor Web page at www.vigorpilot.com. vigorpilot.com will contain up-to-date information on new upgrade parts and radio programming tips, as well as many helpful tips and suggestions from Team JR's pilots to keep you on the cutting edge of Vigor developments and fine tuning.

#### WARNING

The radio controlled model helicopter contained in this kit is not a toy, but a sophisticated piece of equipment. This product is not recommended for use by children. Radio controlled models such as this are capable of causing both property damage and/or bodily harm to both the operator/assembler and/or

spectator if not properly assembled and operated. Horizon Hobby Distributors assumes no liability for damage that could occur from the assembly and/or use/misuse of this product.

#### AMA INFORMATION

We strongly encourage all prospective and current R/C aircraft pilots to join the Academy of Model Aeronautics. The AMA is a non-profit organization that provides services to model aircraft pilots. As an AMA member, you will receive a monthly magazine entitled Model Aviation, as well as a liability insurance plan to cover against possible accident or injury. All AMA charter aircraft clubs require individuals to hold a current AMA sporting license prior to operation of their models. For further information, you can contact the AMA at:

Academy of Model Aeronautics 5151 East Memorial Drive Muncie, IN 47302 (317) 287-1256

#### PRE-ASSEMBLY INFORMATION

When first opening your Vigor kit, you will notice that all of the parts are packaged and numbered to coordinate with the assembly step numbers of this instruction manual.

All small hardware (nuts, bolts, washers, etc.) for each step are separated and packaged separately within the main parts bags. When beginning a section, you will need to open only the bag with the corresponding number to the section you are going to start. It is suggested that you place all of the hardware in an open container (e.g., coffee can) during assembly so as not to lose any of the small parts. It may also be helpful to familiarize yourself with the various sizes of screws, bolts, nuts, etc., as illustrated in the appropriate assembly section before you begin assembly. At the end of each assembly, in most cases, there should be no parts remaining.

Great care has been taken in filling the bags with the correct quantity of parts and hardware for each section. However, occasionally mistakes do happen. In the event that you find a parts shortage or are in need of technical assistance, please contact your local JR Heli Division parts dealer or contact the Horizon Service Center directly.

> Horizon Service Center 4105 Fieldstone Road Champaign, IL 61822 (217) 355-9511 (9am to 5pm CST)



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#### **VIGOR FEATURES**

#### Frame:

- Unique frame design derives structural integrity without the engine
- Stiffness of frame is double to trip conventional designs reduces vibration for improved gyro, engine & powertrain performance
- · Motor mount acts as a jig for easy, goof-proof powertrain alignment
- Straight frame design with full length I-beams can't scissor like conventional "stacked" frames

#### Tail Rotor/Boom:

- · Improved tail control arm offers more precise control, longer life
- · Heavy-duty boom brace ends offer greater rigidity
- Extended sideframe boom mounts provide extremely stiff boom support
- · Reliable belt-driven tail rotor

#### Rotor Head:

- Improved, ultra-true mounting clamp design
- · Swashplate timing is pre-positioned at optimum setting
- Revised delta offset positioning offers improved forward flight stability and reduced boom strike potential
- New lightweight 25 gram paddle design is perfect for 3D or fun flying
- · Flybar weights included

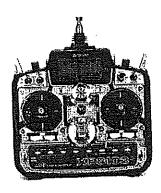
#### Drive Train/Cooling:

- · High-efficiency cooling system increases airflow to double the normal amount
- Main shaft bearing spacing is 50% wider than conventional designs for superior rigidity
- Additional BB engine drive pinion gear support keeps power loads from being introduced to the engine
- New, larger 20 oz. fuel tank for extended flight times

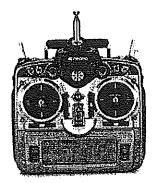
# ITEMS REQUIRED TO COMPLETE THE JR VIGOR

# 1. RADIO SYSTEM REQUIREMENTS (NOT INCLUDED):

6-channel or greater R/C helicopter system with 5 servos, 1400mAh receiver battery and gyro.



JR XP8103



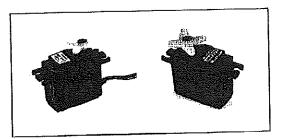
JR PCM10X



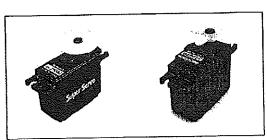
JR G450 Gyro



Receiver



JRPS8101 Ultra Precision OR JRPS8231 Ultra Precision Digital Alleron, elevator, collective, throttle servos



2700G High Speed Super OR 8417 High Speed Digital

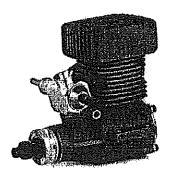
Tail rotor servos



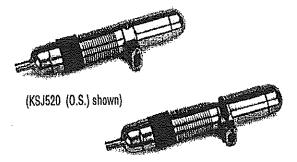
JRPB4340 1400mAh battery pack

A .60 - .61 R/C helicopter engine is required.

A special helicopter type muffler is also required.



(Webra .61P5 heli engine shown)



(KSJ583 (YS) shown)

## 3. BUILDING SUPPLIES (NOT INCLUDED):

The following items are needed to complete the assembly of the JR Vigor:



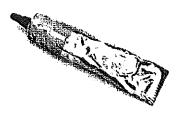
Fuel Filter



Medium Silicone Fuel Tubing (3 ft.)



Double Sided Servo Mounting Tape



High Speed Grease



Nylon Wire Ties (to secure radio wires)



Glow Plugs (HAN3020)



Light Oil

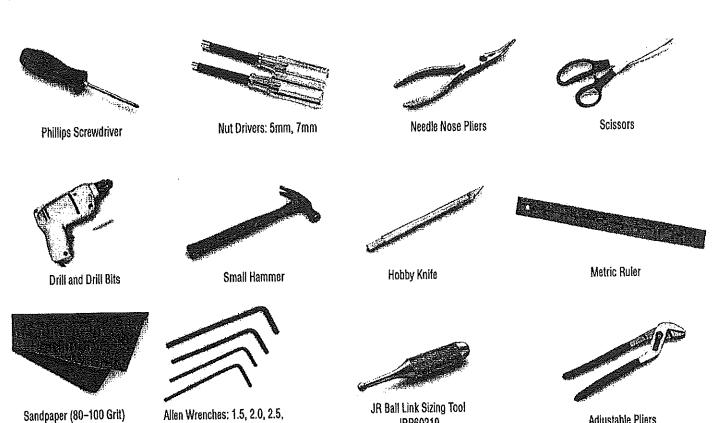


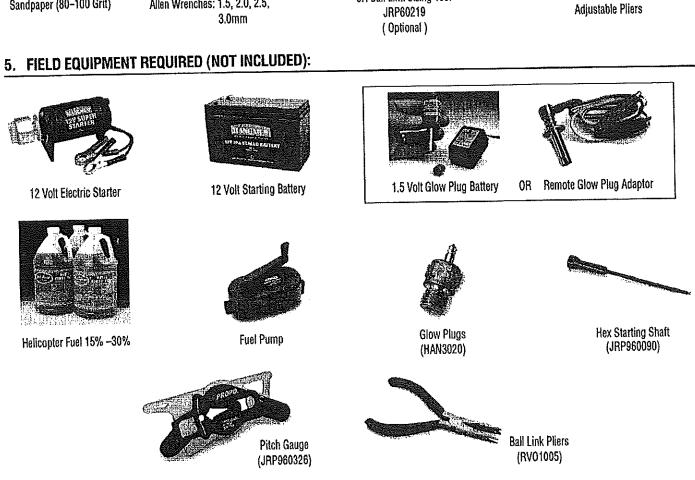
Rubbing Alcohol



Red & Green Threadlock

# 4. TOOLS NEEDED TO ASSEMBLE THE JR VIGOR (NOT INCLUDED):



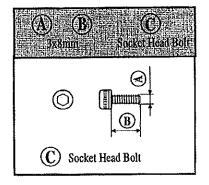


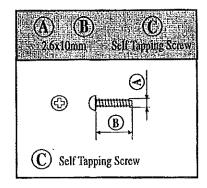
# HARDWARE IDENTIFICATION

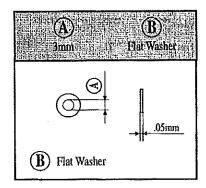
There are a variety of sizes and shapes of hardware included in this kit.

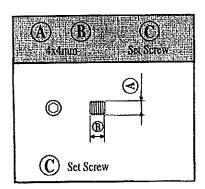
Prior to assembly, please be careful to identify each screw by matching it to the full size screw outlines included in each step.

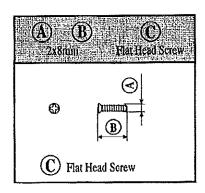
All of the hardware, screws, nuts, etc., contained in the Vigor kit are described in the following A, B, C manner:

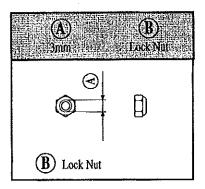


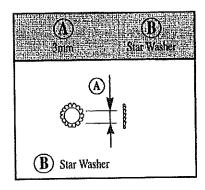


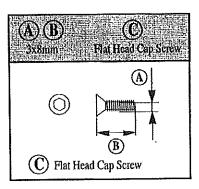


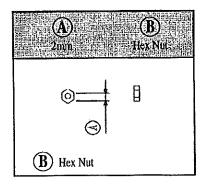






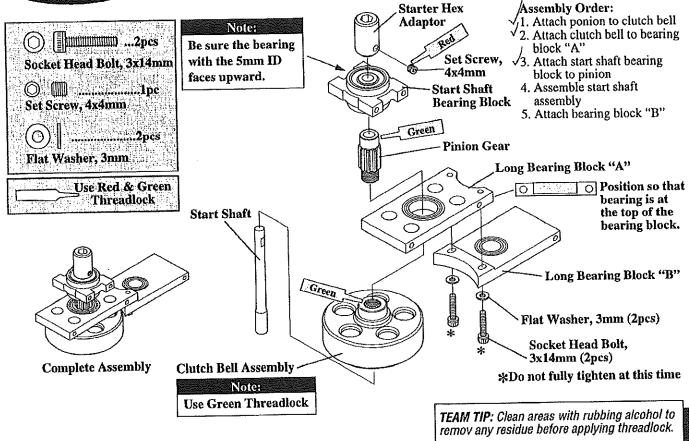






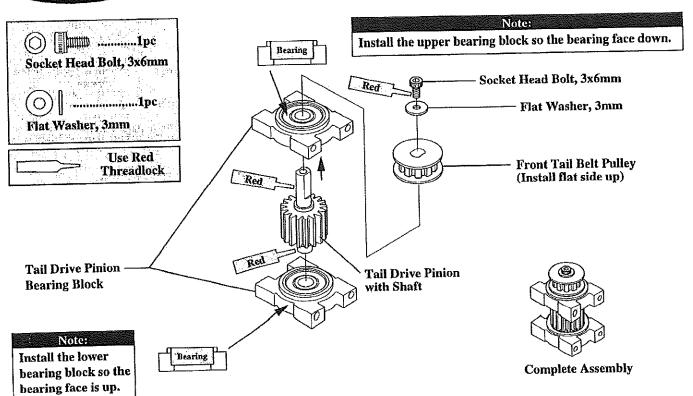


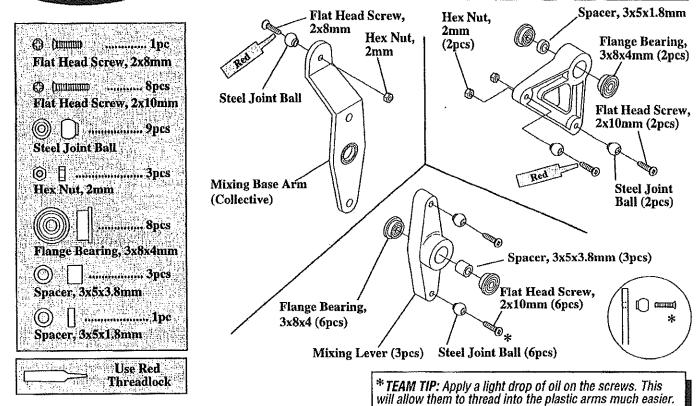
## CLUTCH BELL/START SHAFT ASSEMBLY



# 1-2

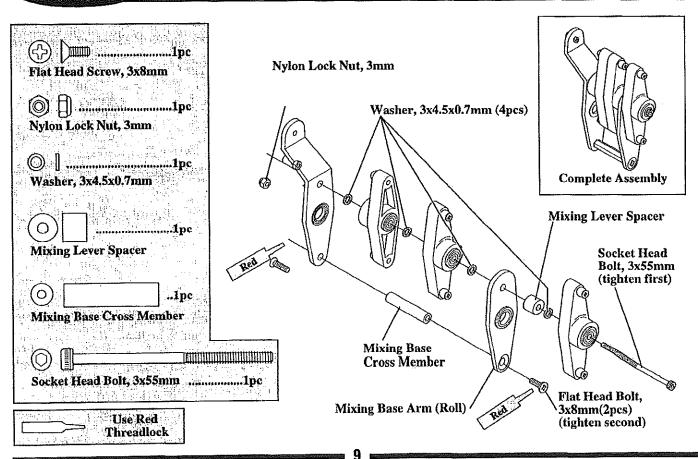
# TAIL DRIVE PINION/ BEARING BLOCK ASSEMBLY



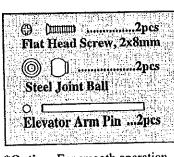


1-4

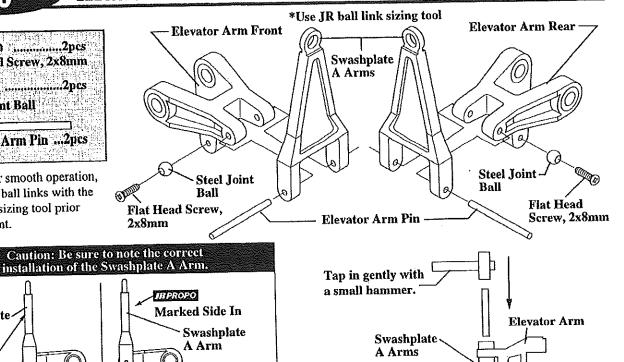
## **SERVO MIXING LEVER UNIT ASSEMBLY**



# **ELEVATOR ARM ASSEMBLY**



\*Option: For smooth operation, pre-size the ball links with the JRball link sizing tool prior to attachment.



Edge of Workbench

**Elevator Arm Front** 

Marked Side Out

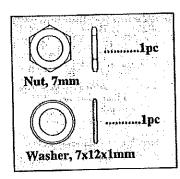
Swashplate-

A Arm

TR PROPO

## **FUEL TANK ASSEMBLY**

**Elevator Arm Rear** 



Fuel Tank Clunk Silicone Tube (small) Nipple Medium Silicone Fuel Tubing (not included) Connect to Engine Carburetor

1. Cut the small silicone Fuel Tubing(included) to a length of 77mm. Next, connect the Fuel Tank Clunk, Nipple, and Medium Silicone fuel Tubing (not included) as shown above.

Use two Wrenches if

Nipple.

necessary to secure Tank



2. Insert the assembly into the Fuel Tank opening so that the Nipple is inside the tank. Next, slide the Fuel Tank Grommet over the medium Fuel Tubing.



Make sure grommet is fully seated.

3. Inset the Fuel Tank Grommet into the Fuel Tank opening.



making sure that it is fully seated.



6.Complete Assembly

Nut, 7mm 5. Remove the medium Silicone Fuel Tubing from the Nipple and secure the Nipple to the Fuel Tank using the 7x12x1mm Washer and 7mm Nut supplied. Be sure to secure this assembly firmly to avoid leakage.

Washer, 7x12x1mm

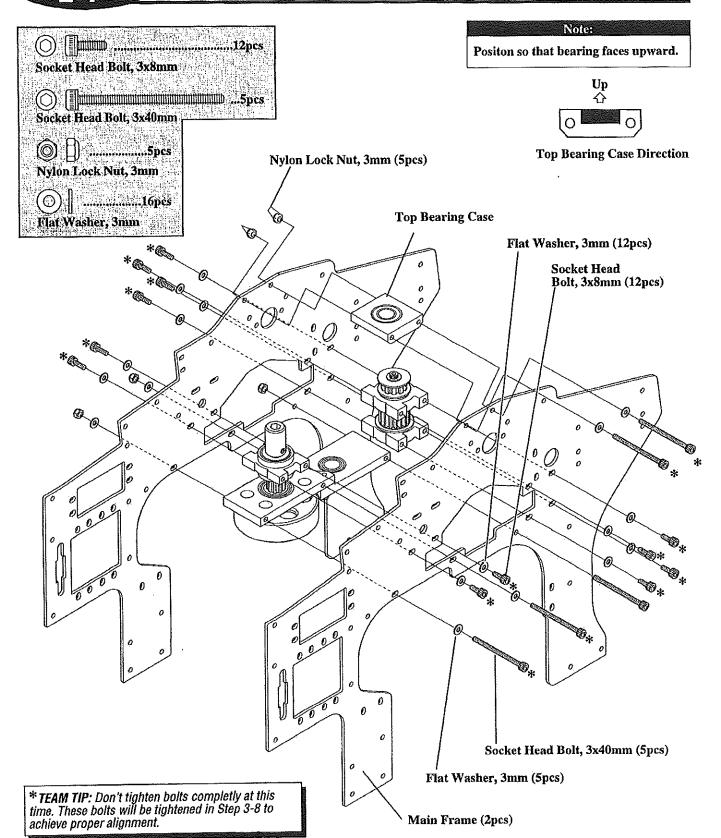


4. Pull the medium Fuel Tubing out of the Fuel Tank unit the threads of the Fuel Tank Nipple are exposed.

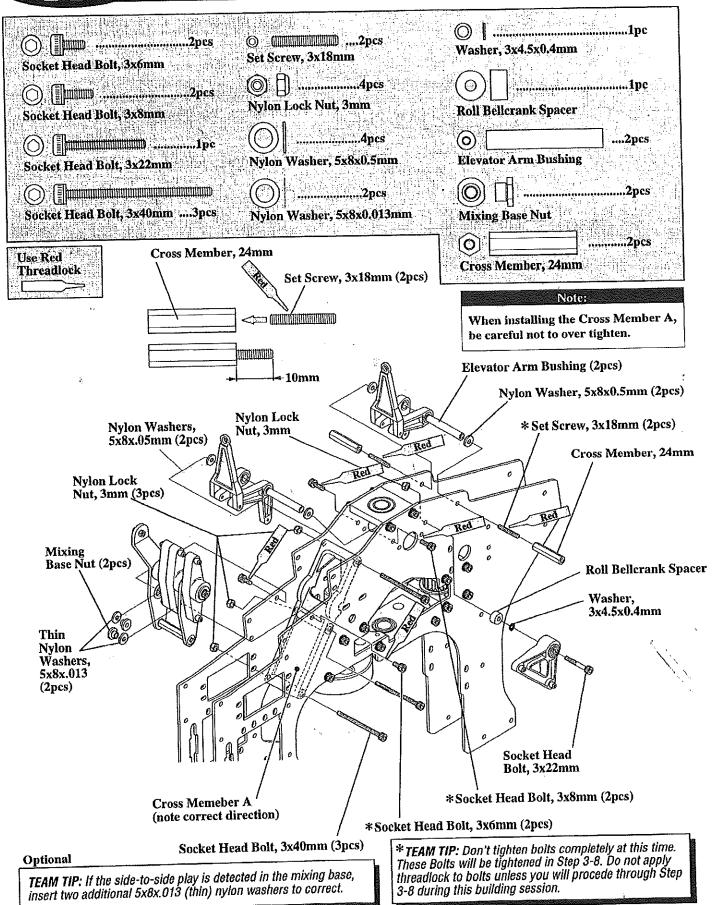


Pull out until Nipple threads are exposed.

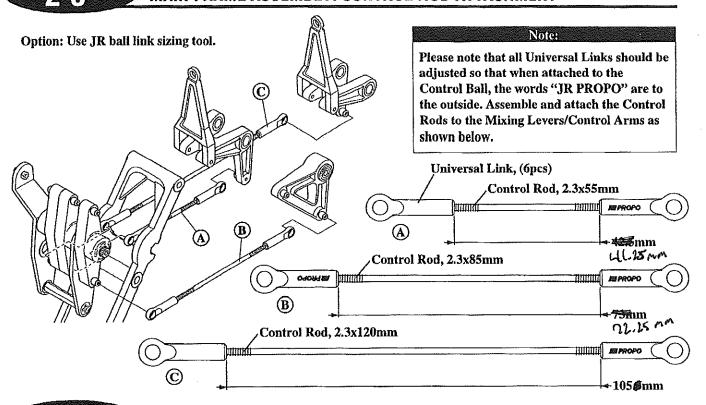
10



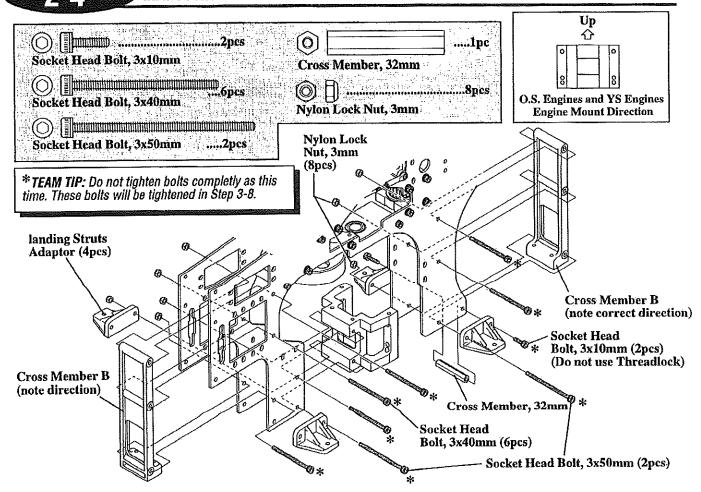
# MAIN FRAME ASSEMBLY: CONTROL LEVER INSTALLATION

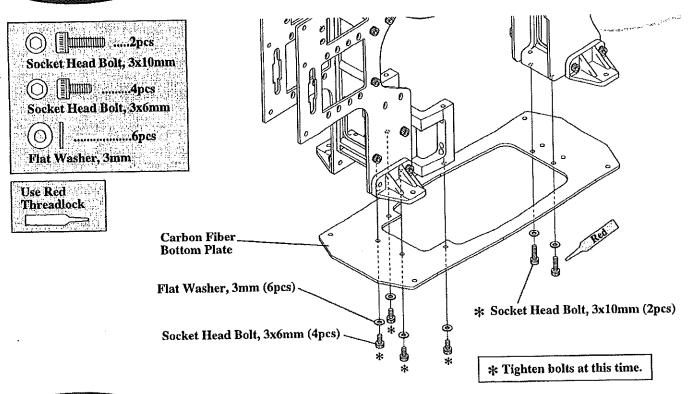


### MAIN FRAME ASSEMBLY: CONTROL ROD ATTACHMENT

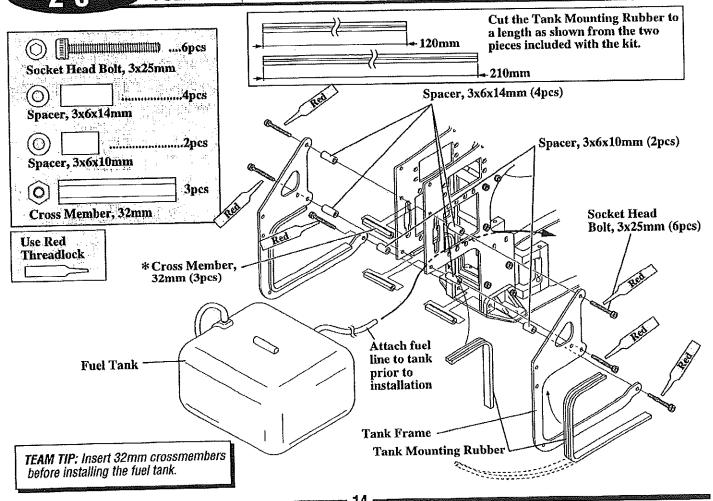


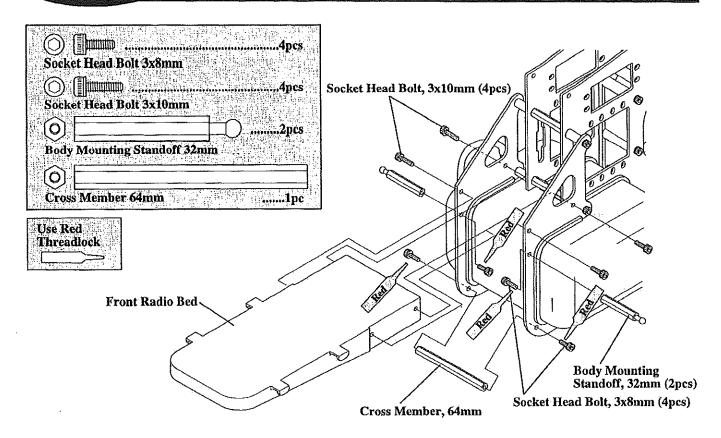
### MAIN FRAME ASSEMBLY: ENGINE MOUNT CROSS MEMBER INSTALLATION





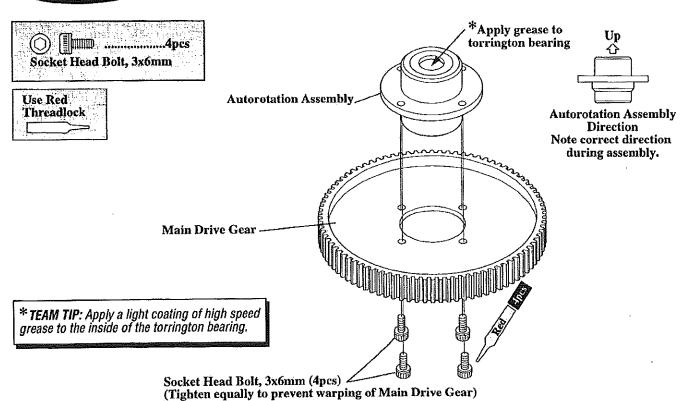
2-6 FUEL TANK INSTALLATION

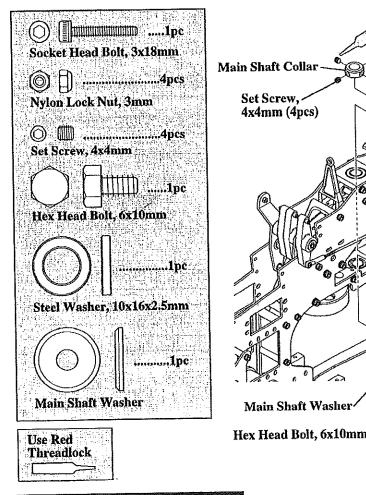


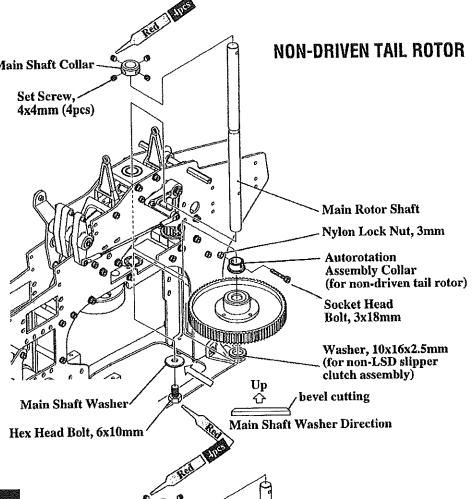


# 3-1

## MAIN DRIVE GEAR/AUTOROTATION ASSEMBLY







#### LSD Slipper Clutch

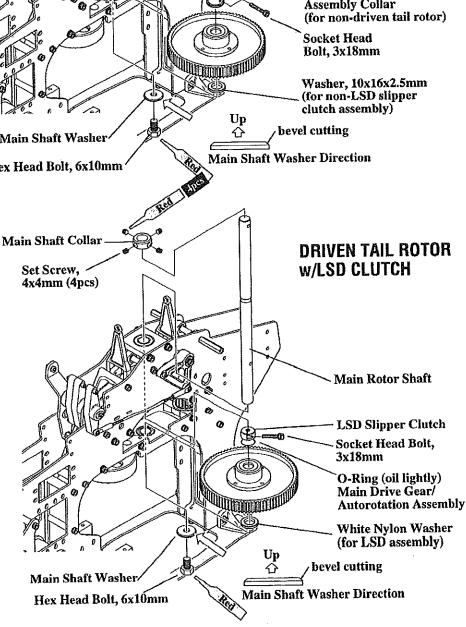
Your Vigor kit includes parts that will give you Your Vigor kit includes parts that will give you the option to complete this assembly in standard configuration (non-driven tail rotor), or with the LSD (Limited Slip Differential) Slipper clutch. The LSD Slipper Clutch will allow the tail rotor to be partially driven during autorotations. This will allow the pilot to have tail rotor control during autorotations, which is necessary for maneuvers like a 180 degree autorotations, rolling autos, etc.
The LSD Slipper Clutch will also prevent the model from rotating at the very end of an autorotations.

When using the LSD clutch, it is important to note that the tail rotor pitch will need to be adjusted due to the fact that the tail rotor is now operational and can cause the model to yaw during an autorotation.

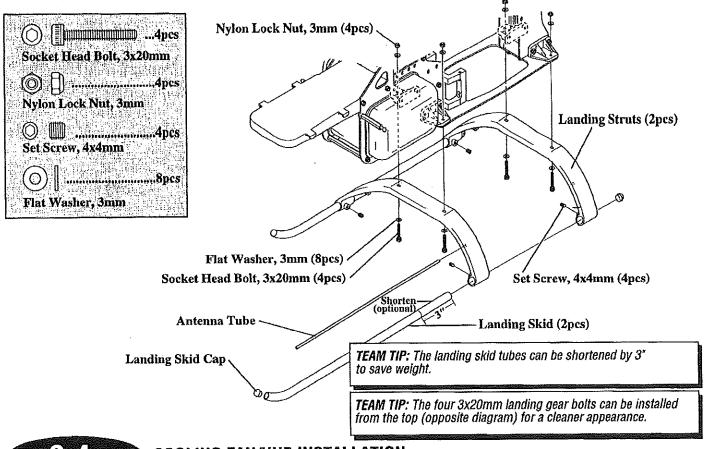
You will find a separate package in your kit that contains the necessary parts to install the LSD Slipper Clutch. When using the LSD unit, the following parts will not be needed: 1- Steel Washer, 10x16x2.5mm

- Socket Head Bolt, 3x18mm
- Lock Nut, 3mm
- 2- Autorotation Assembly Collar

Once the Main Shaft Assembly has been installed per the instructions, the LSD unit can be secured into position with the included 3x18mm Socket Head Bolt. When securing, apply a small amount of downward pressure to the LSD unit so that the o-ring will be slightly compressed. Final adjustment of the LSD unit can be made once the tail rotor assembly has been completed.

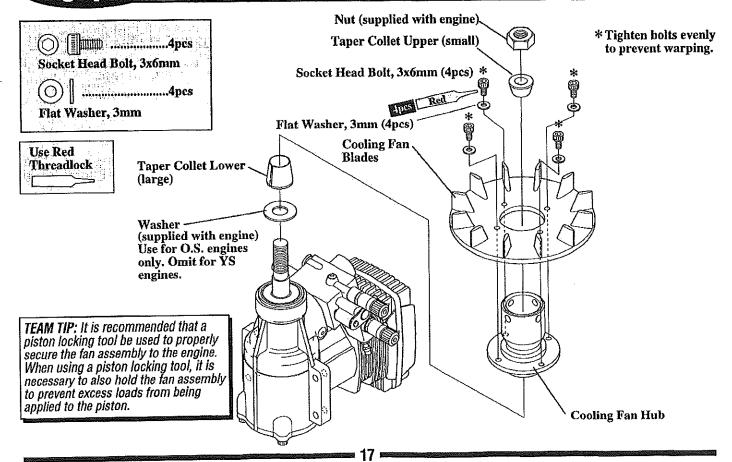


#### LANDING GEAR ASSEMBLY INSTALLATION

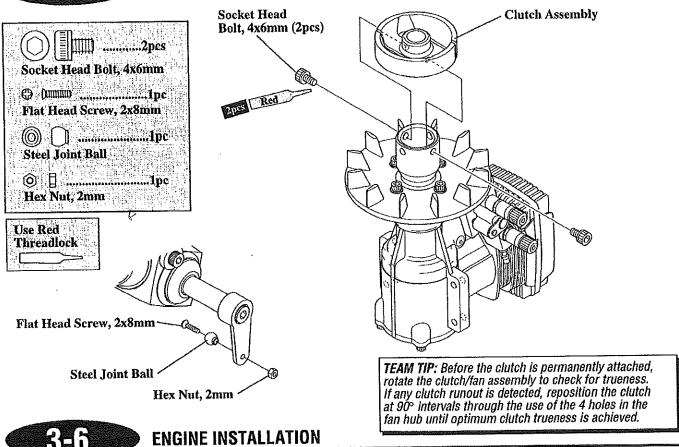


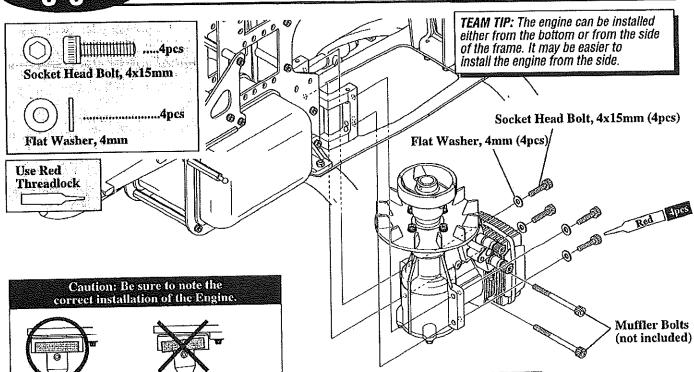
3-4

#### **COOLING FAN/HUB INSTALLATION**



### **CLUTCH ASSEMBLY ATTACHMENT**





1, Adjust the position of the engine as shown so the bottom of the Clutch Assembly is flush with the bottom of the Clutch Bell. Also check to insure that the Engine and Clutch Bell are parallel.

2, It is highly recommended that you insert the Muffler Bolts into the Engine Case prior to installing the engine in the frame.

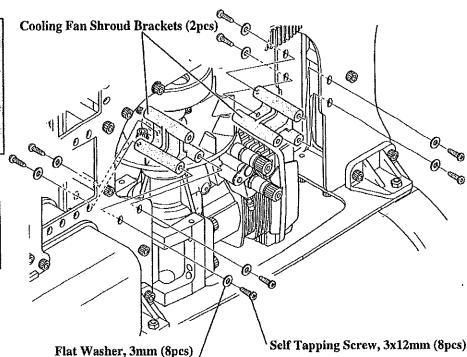
#### **COOLING FAN SHROUD BRACKET ATTACHMENT**



Do not tighten screws at this time. They will be tightened in Step 3-9.

#### Note:

Do not tighten screws at this time. They will be tightened in Step 3-9.



#### **BOLT TIGHTENING ORDER/GEAR MESH ADJUSTMENT**

Use Red Threadlock **Bolt Tightening Order:** 

1. Motor Mount to Main Frame Plates 2. Start Shaft Bearing Block/Bearing Blocks "A" & "B"

3. Crossmember "A", and front Crossmember "B" to Main Frame Plates
4. Upper Main Shaft Bearing Block to Main Frame Plates

5. Rear Pinion Bearing Blocks (2) to Main Frame Plates 6. Rear Crossmember "B" to Main Frame Plates

7. Tighten all remaining bolts on frame left loose from Steps 2-1, 2-2 and 2-4

not to make contact with the

Main Rotor Shaft.

7 Tighten all

remaining bolts

#### Gear Mesh Adjustment

Once the engine has been installed, adjust the gear mesh of both the main and tail pinions so that a slight amount of 'backlash" is achieved. One method for achieving the proper clearance is to insert a folded piece of paper between the two gears, press the gears together, then secure the bearing blocks in place. When setting the gear mesh, make sure that the two pinion gears remain parallel to the main drive gear teeth, as it is possible to alter the pinion gear angle during adjustment.

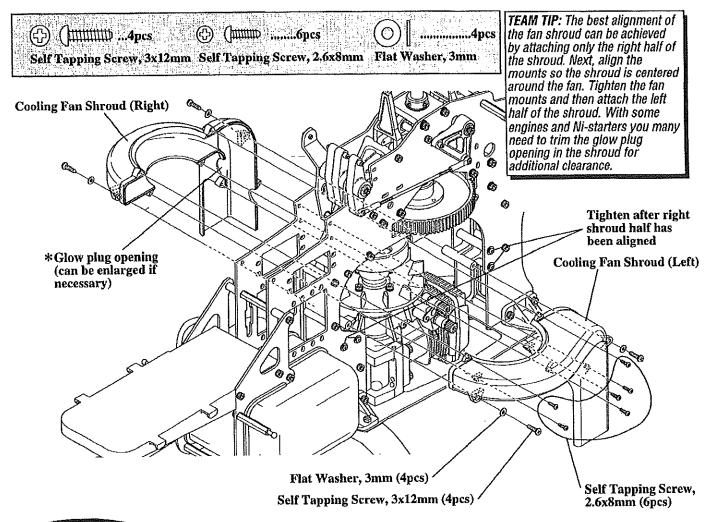
If you find difficulty achieving proper alignment of the main pinion, it is also possible to loosen the six bolts that attach the engine mount to the main frame. This will allow the engine/ mount to be repositioned slightly to achieve the proper gear

Once the desired gear mesh has been achieved, tighten all bolts left loose from Step 2-1. Please remember to use threadlock on the bolts securing the upper start shaft pinion block, as well as the two tail pinion bearing blocks.

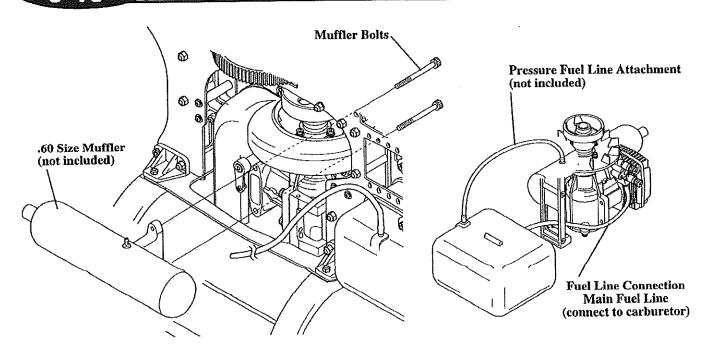
Please also remember to apply threadlock and tighten the two 3x14mm socket head bolts that connect bearing block "A" to bearing block "B." (see Step 1-1 for details).

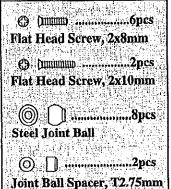
TEAM TIP: Once the gear mesh/engine alignment has been established, rotate the start shaft assembly first counterclockwise, then clockwise. When moved clockwise, the start shaft assembly should move freely with little or no resistance. If resistance is present, this means that the clutch/start shaft assembly are not aligned properly. Readjust as necessary.

0 \* 2 When securing the front Elevator Arm Bolts make sure that the assembly is positioned as far forward as possible so as

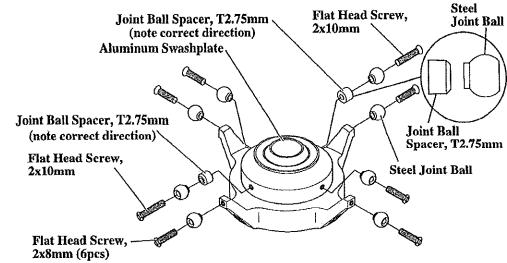


# 3-10 INSTALLATION OF THE MUFFLER/FUEL LINE CONNECTIONS



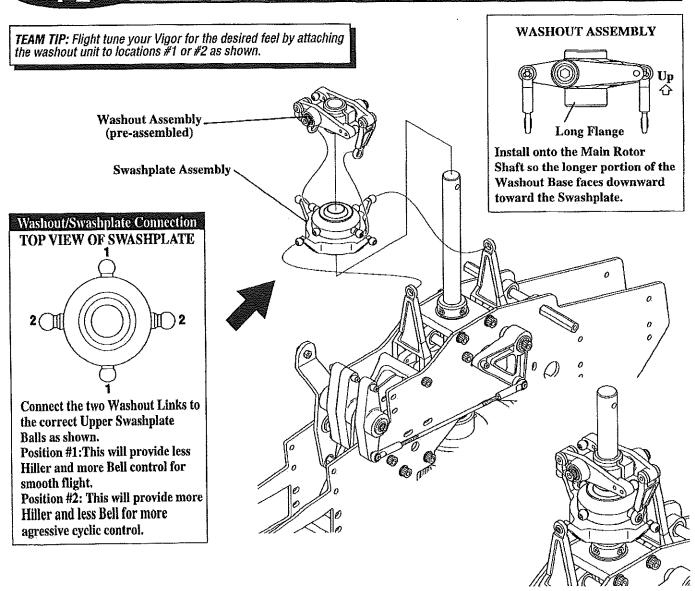


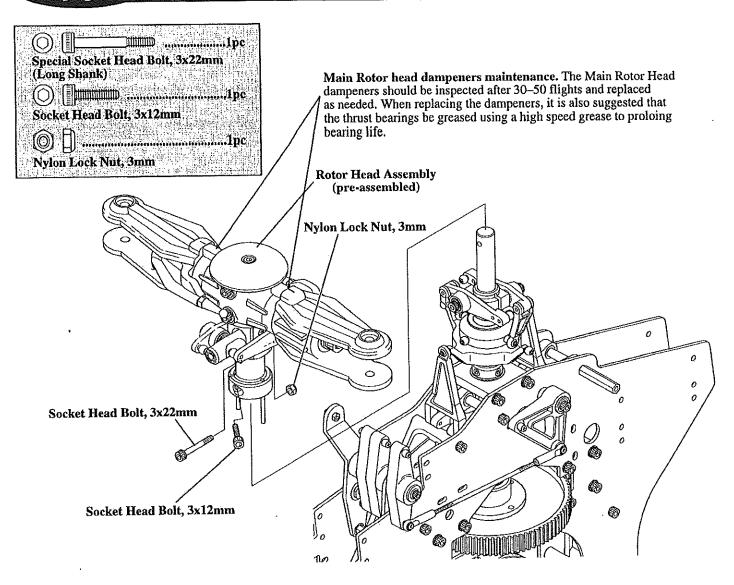
Use Red Threadlock on all Screws

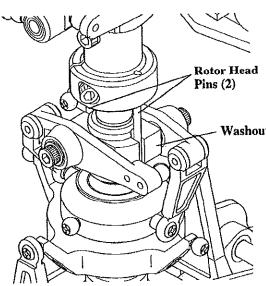


41-2

## SWASHPLATE/WASHOUT ASSEMBLY INSTALLATION







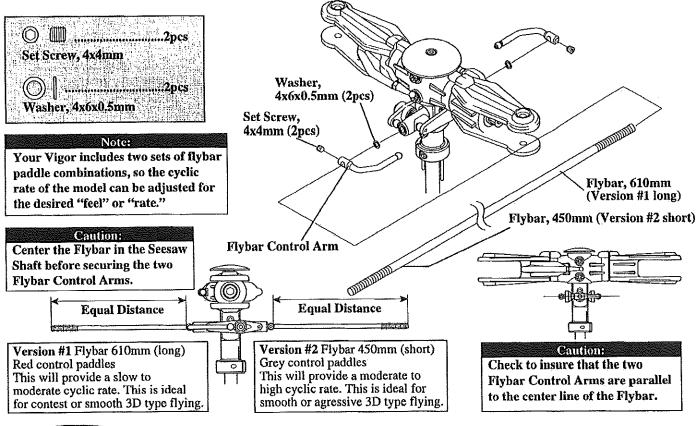
TEAM TIP: For safety, it's important to note that a hardened bolt with a long shank should be used to attach the rotor head. I have seen many people, over time, replace these with standard bolts. This increases the chances of failures in flight.

**Washout Base Driver** 

#### Note:

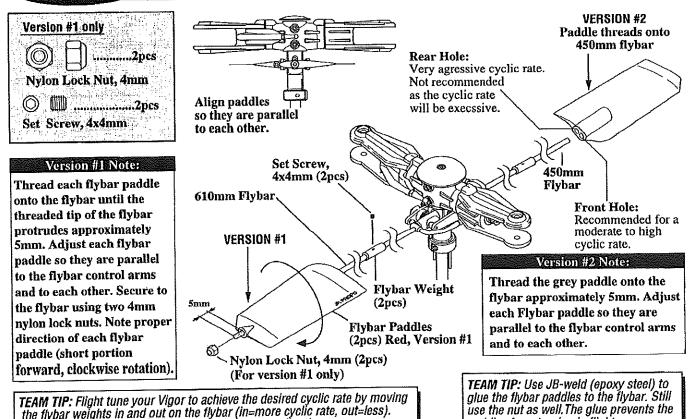
Be sure to engage the Rotor Head Pins (2) into the Washout Base Driver before securing the Rotor Head Assembly in place.

#### **FLYBAR INSTALLATION**

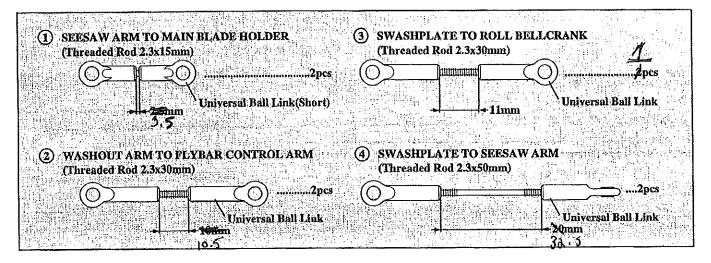


#### FLYBAR PADDLE ATTACHMENT

TEAM TIP: Flight tune your Vigor to achieve the desired cyclic rate by moving the flybar weights in and out on the flybar (in=more cyclic rate, out=less). Make sure that they are set to the same distance or vibration can occur.



paddles from turning in flight.



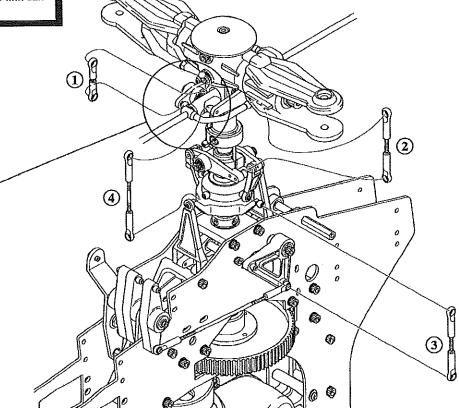
TEAM TIP: The JR ball links are designed with little ridges around the lip of the link. These ridges, in conjunction with the JR ball link sizing tool, are there to help you custom fit the link to the ball. If the link fits on the ball too tight you can use the reaming tool to enlarge the link hole size. If the link fits too loose on the ball you can push in on the ridges on the link with a small pair of pliers. This reduces the size of the link hole and makes the link fit tighter. JR links are some of the best links available. It is important to note that very little force is needed on the ridges to resize the link. Using pliers on any other part of the link can cause the links to break.

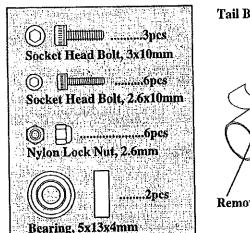
TEAM TIP: After many flights there can be excess play between the ball and link. It is usually the ball that has actually worn. So when replacing parts, you will actually get the best results by replacing the balls.

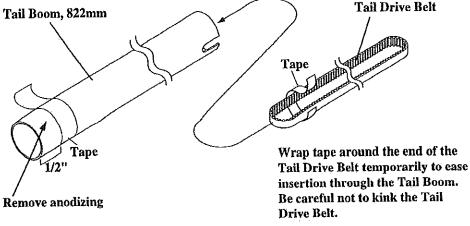
#### Caution:

Please note that all Universal Links should be adjusted so that when attached to the Control Ball, the words "JR PROPO" are to the outside.

Note: the seesaw mixing arms included with the Vigor are designed to offer a pitch range of approx. 20° (+11°, -9°). If additional pitch range is required, it is possible to replace these arms with part #JRP960178B. These arms will provide a total pitch range of 23° (+13°, -10°). Please note that these optional mixing arms will also increase the "Bell" movement of the Rotor Head, which will alter the flight characteristics slightly. Please refer to Step 8-5 for assembly and installation information of these optional arms. Also note that if these optional arms are used, the overall pitch and travel values may vary from that shown in the data sheets included in this manual (page 53).

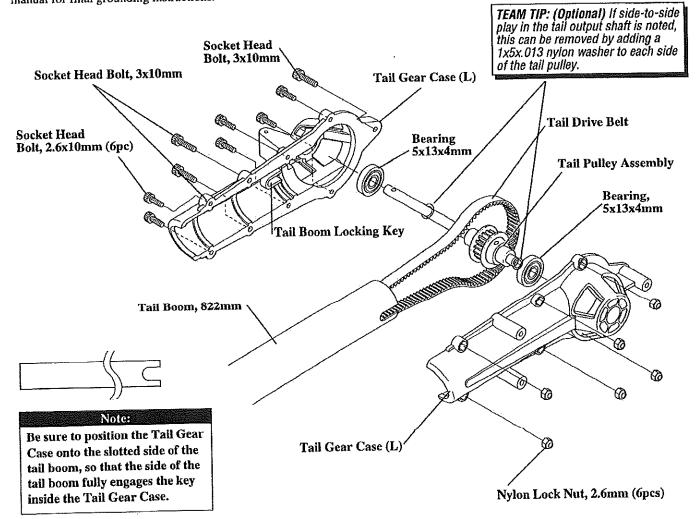




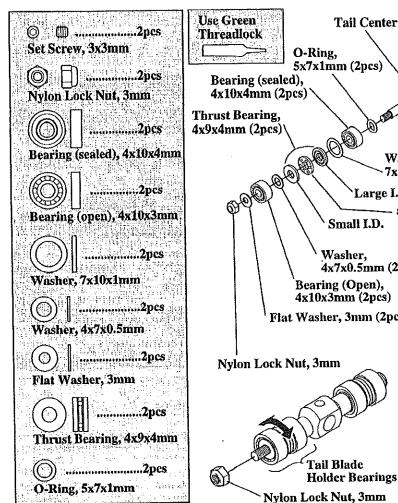


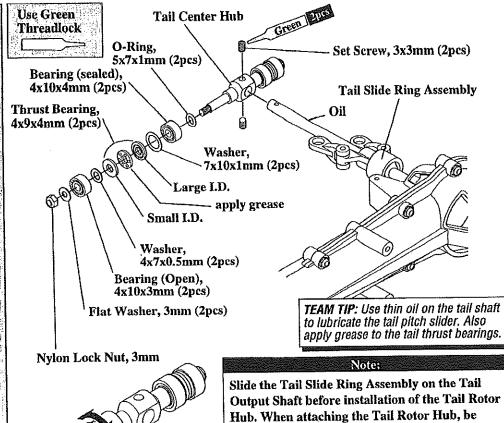
IMPORTANT: Removing anodizing from the tail boom for proper grounding

Prior to inserting the Tail Drive Belt, it will first be necessary to remove the anodized coating (black) from the end of the tail boom opposite of the Tail Case. To do this, apply a piece of masking tape to the end of the tail boom so that approximately 1/2" of the tail boom is exposed at the end. Using 80 grit sandpaper, or a Moto-Tool with a sanding drum, remove the black coating or the tail poom is exposed at the end. Using 80 grit sandpaper, or a proto-1001 with a sanding drum, remove the black coating from the end of the tail boom. Removal of the anodized coating is mandatory to achieve proper grounding of the tail boom assembly to the main frame of the helicopter. This procedure must be followed or possible RF radio interference can occur with some systems. This radio, or RF interference can occur during operation as "static" is produced by the tail drive assembly. This "static" can be found in most types of tail rotor systems that incorporate a belt for the tail drive. Testing has shown that by groundingthe tail assembly to the main frame, the possibility of radio interference is eliminated. Please refer to Section 5-6 of this manual for final grounding instructions.



#### TAIL CENTER HUB ASSEMBLY





green threadlock.

certain that the Set Screws 3x3mm engage into

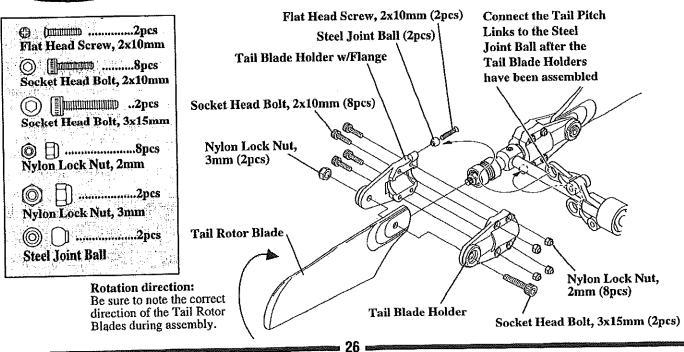
the holes at the end of Tail Output Shaft. Use

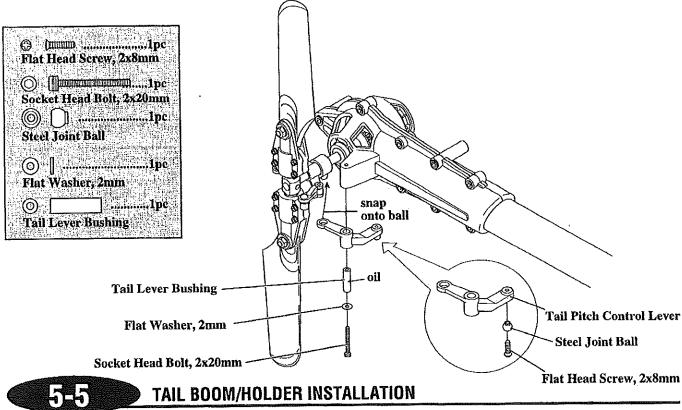
Check to make sure the Tail Blade Holder

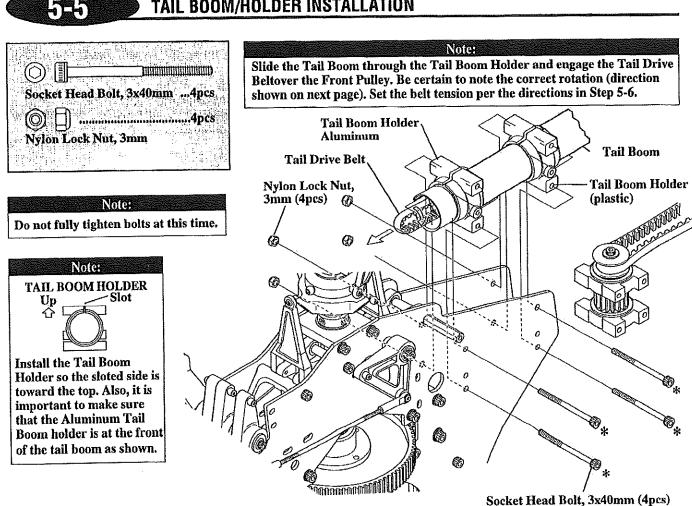
Bearings can rotate freely, without play. If binding occurs, loosen the 3mm Nylon Lock Nut.

5-3

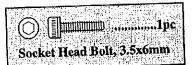
# TAIL BLADE HOLDER ASSEMBLY





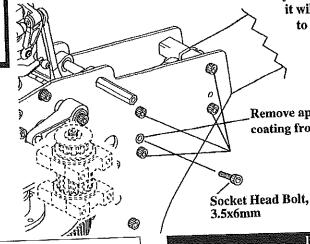


# TAIL BELT ADJUSTMENT/TAIL BOOM GROUNDING



TEAM TIP: It is best for the belt to be run tight all the time. A loose belt will slip during aggressive 3D flight and also wear quicker than a tight one. As mentioned in Step 5-1, it will be necessary to ground the tail assembly to the main frame of the model to prevent the possibility of radio RF interference caused by "static" from the tail drive during flight. To create a secure ground for the tail assembly, it will be necessary to remove a 1/4" diameter portion of the black powder coating from the left side of the main frame at the location shown in the diagram. Next, install the 3.5x6mm socket head screw into this location and secure. Please note that since this screw is designed to thread only into the aluminum tail mounting clamp,

it will not be necessary to loosen this screw to make belt tension adjustments.



Remove approximately 1/4" of the black powder coating from the frame at this hole location.

Tighten temporarily installed Bolts, making sure the Tail Output Shaft is exactly 90 degrees to the Main Rotor Shaft.

#### **Belt Tension**

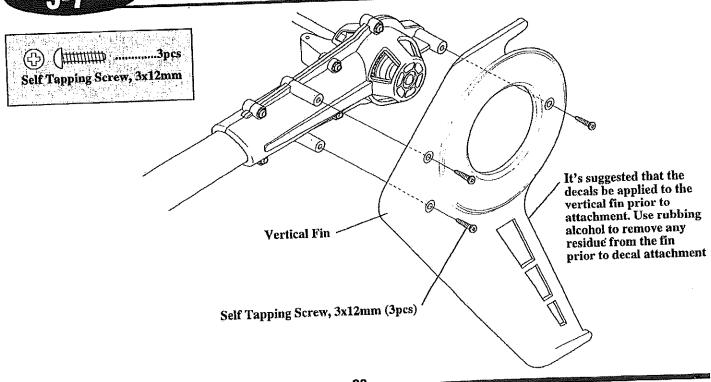
Belt tension should be set so when pressing with your finger, both sides of the belt does not come in contact with each other. It is recommended to set the belt tension slightly tight at first to prevent slipping and loss of tail drive. Rotate the Tail Drive Belt in the direction shown before installing it onto the front pulley. It is extremely important to install the belt in the proper direction to insure correct rotation of the Tail Rotor Blades.



Front Pulley

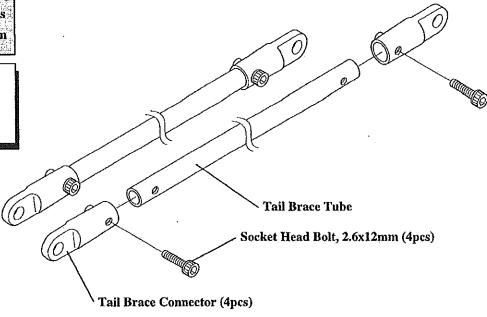
# **VERTICAL FIN ATTACHMENT**

TailOutput Shaft Pulley



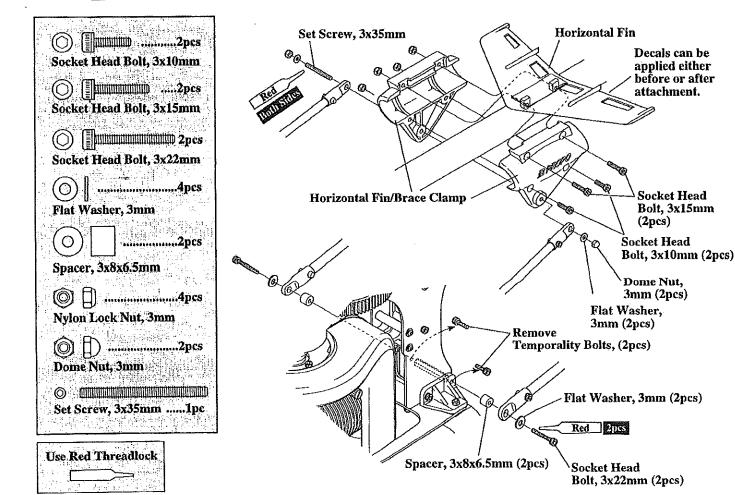


TEAM TIP: It is suggested that the Tail Brace Connectors be bonded to the Tail Brace Tubes using either thick CA adhesive, or JB Weld.

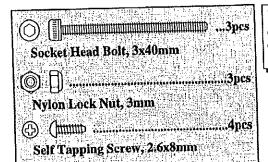


5-9

# TAIL BOOM BRACE/HORIZONTAL FIN INSTALLATION

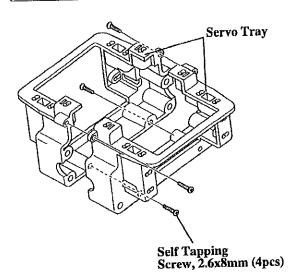


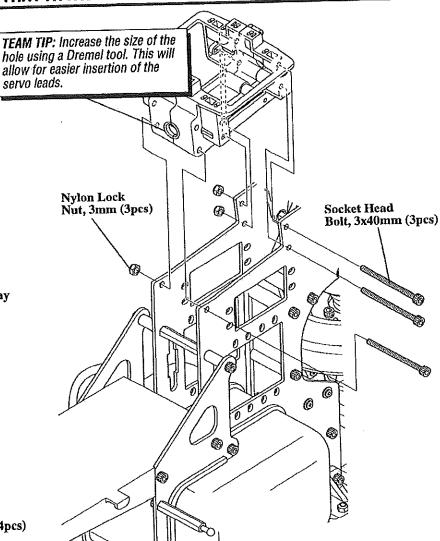
# **UPPER SERVO TRAY ATTACHMENT**



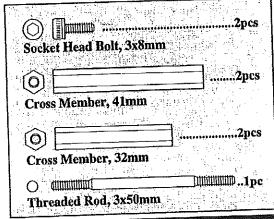
Note:

When installing the Servo Tray, be careful not to overtighten.



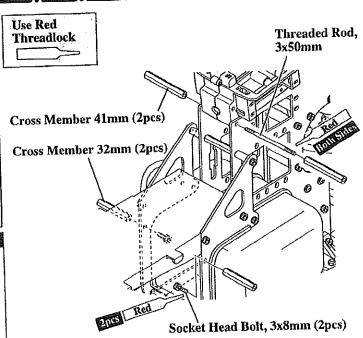


# OPTIONAL BODY MOUNT ATTACHMENT

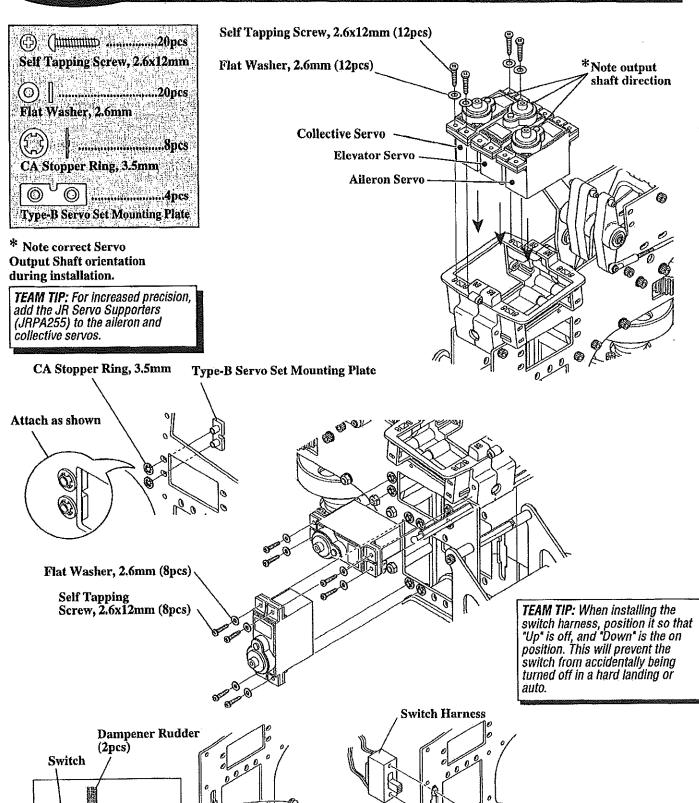


#### Caution:

If you want to attach the Body very firmly, install the extra 41mm Cross Member, and change to the extra 32mm Cross Member as shown. (In such a case, you can attach the Body at six places with socket head screws). This will provide a more secure canopy mount for 3D type flying.



**Switch Plate** 



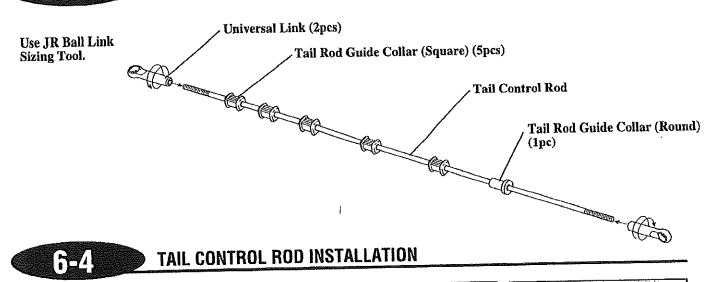
Rubber (2pcs)

On

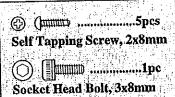
Switch Dampener

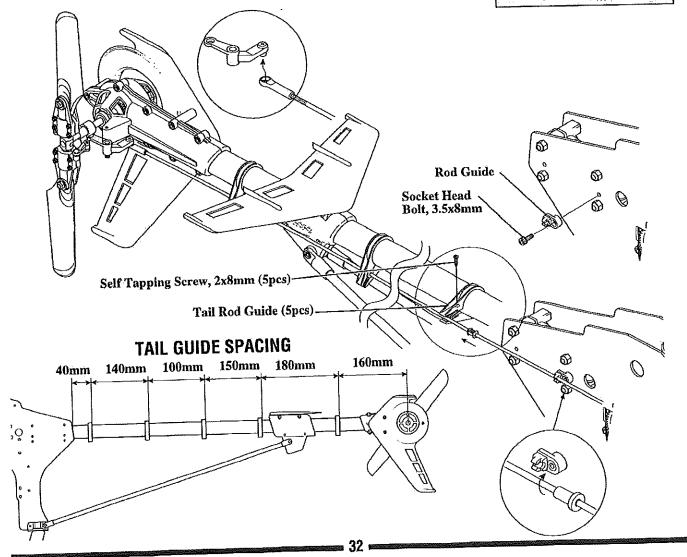
Screws Supplied

with Switch



**TEAM TIP:** Once tail guides are attached to the tail boom, check to insure that the tail control rod will move freely with little resistance. Rotate the tail guides as needed until the system moves as easily as possible. Once this has been achieved, apply a small amount of CA adhesive to bond the tail guides to the tail boom. This will prevent the guides from being moved accidentally.

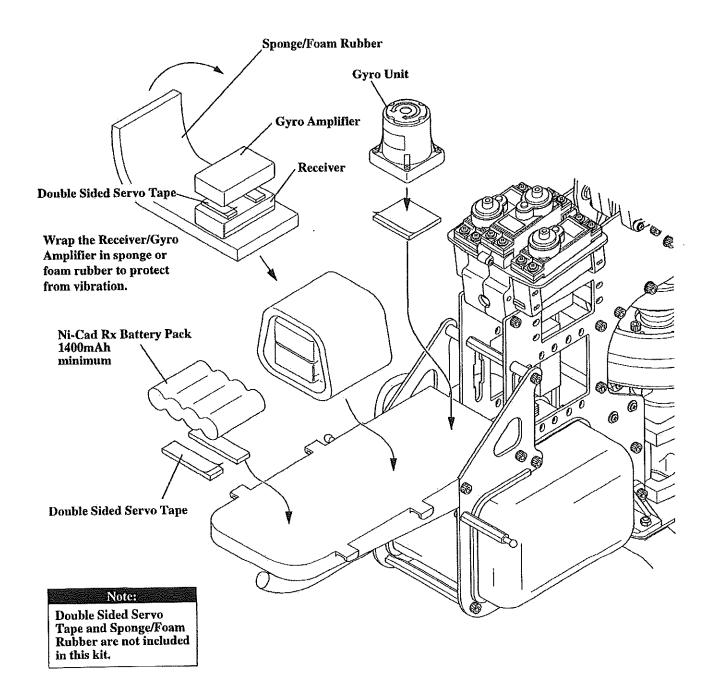




#### Note:

Be certain when installing the Gyro Unit to the Front Radio Bed that it does not come in contact with the frame of the helicopter, etc.

Also make sure that the Front Radio Bed is free from oil and debris. Clean with rubbing alcohol if necessary to insure proper adhesion.



# RADIO SYSTEM PREPARATION

The following preparations are suggested for use with JR radio systems. However, these procedures are applicable to most other brand radio systems. These suggested adjustments are necessary to insure correct installation and attachment of the control linkages and servo horns.

### TRANSMITTER PREPARATION

- Set all trim levers, trim knobs and switches to the neutral, or zero, positions.
- 2. Turn the transmitter power switch to the "on" position.
- 3. If you are using a computer radio system that had been previously adjusted
- to another model, reset all functions and input values to the factory preset position.
- Move the throttle/collective control stick to the center or half stick position. Next slide the throttle trim lever to the full low position.

# RECEIVER FLIGHT PACK PREPARATION

- With the transmitter still on, slide the receiver switch to its "on" position. All servos should move to the neutral, or center, position.
- Check to insure that all servos operate with the appropriate control stick.
- 3. Rest the throttle stick to the center position, making sure the throttle trim is still at low.
- 4. Turn off the receiver switch first, followed by the transmitter.

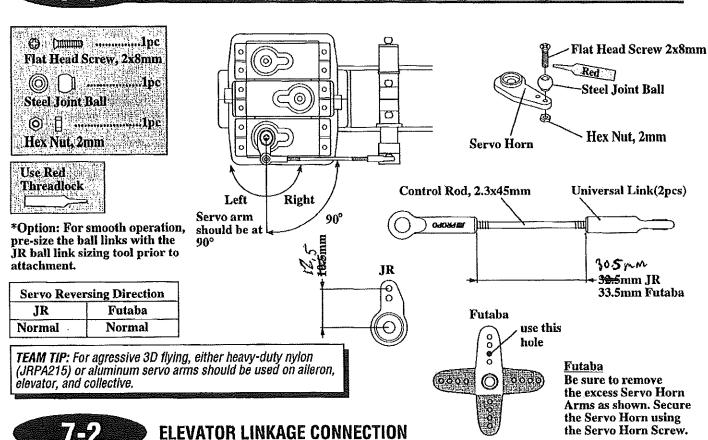
# SERVO HORN INSTALLATION SUGGESTIONS

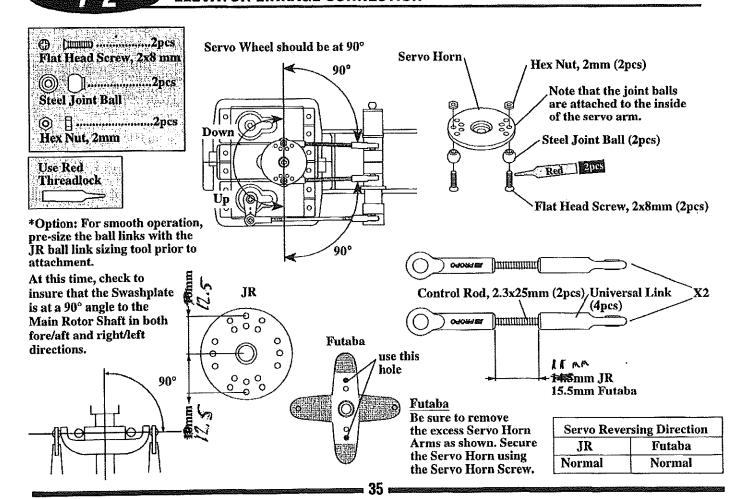
For proper operation, it's important that the servo horns are positioned on the servos in the "exact" neutral position. Although most computer radio systems offer a sub-trim feature, it is suggested that the servo horns be manipulated on the servos to achieve the "exact" neutral settings.

Since the servo output spline on a JR system has an odd number of teeth (21), it's possible to reposition the servo arm on the servo at 90° intervals to achieve the proper neutral attachment of the servo horn.

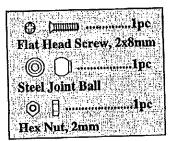
Once the correct arm of the servo horn has been established, it's suggested that the remaining unused arms be removed from the servo horn as shown in the installation diagrams in the following section.

It will also be necessary to enlarge the appropriate hole in the servo horn slightly to allow correct installation of the steel control balls to the servo horn.





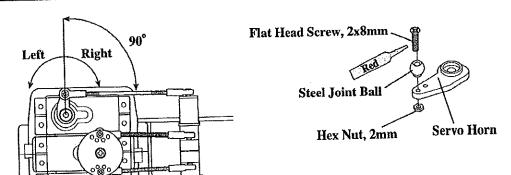
# **COLLECTIVE PITCH LINKAGE CONNECTION**

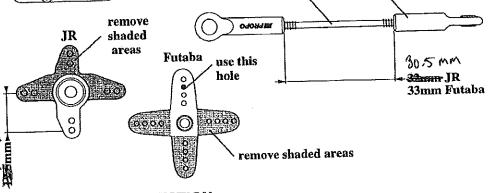


Use Red Threadlock

\*Option: For smooth operation, pre-size the ball links with the JR ball link sizing tool prior to attachment.

Servo Reversing Direction				
JR	Futaba			
Reverse	Reverse			

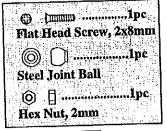




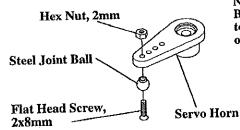
Control Rod, 2.3x45mm

7-4

# TAIL CONTROL ROD CONNECTION



Adjust the length of the Tail Control Rod until both the Tail Pitch Lever and Servo Arm are at 90° as shown below.

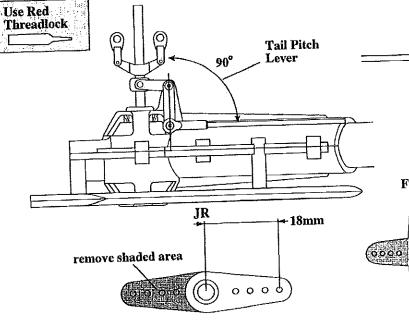


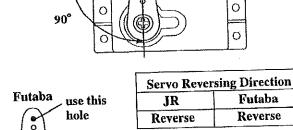
Note that Control Ball is attached to the inside of the Servo Arm.

Servo should be at

90° at nuetral

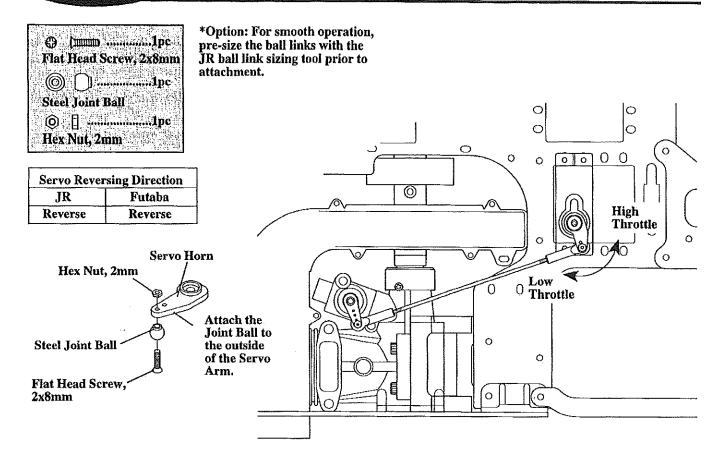
Universal Link (2pcs)

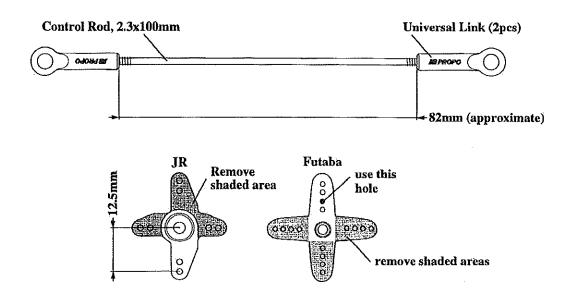




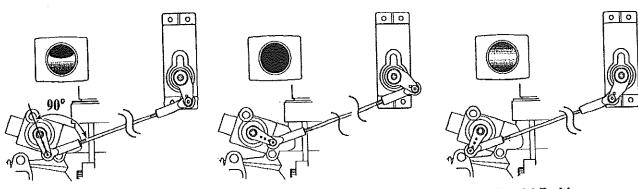
remove shaded areas

O 29





### THROTTLE ARM/SERVO HORN POSITIONS



1/2 Stick (Throttle) Position (Throttle Barrel 1/2 open)

High Stick (Throttle) Position (Throttle Barrel Fully Open)

Low Stick (Throttle) Position (Throttle Barrel Fully Closed)

\*To avoid differential throttle travel, make certain both the throttle arm and the servo horn are positioned as shown in the above diagrams.

To achieve the correct position of the throttle/servo arm, it may be necessary to re-position the throttle arm on the carburetor. It may also be necessary to adjust the length of the throttle linkage slightly to achieve full open and closed positions of the carburetor.

### Throttle Travel Adjustment (Initial Set-Up Only)

It is also possible to increase/reduce the travel of the throttle servo through the travel adjust function found in most computer radio systems. If this function is used, make sure the values for the high and low positions remain equal (same value for high/low). If these values are not equal, it will create a differential, or uneven movement of the throttle, making rotor rpm adjustment and fine tuning more difficult.

### Throttle Travel Adjustment (Full 3D Set-Up)

When setting up your throttle linkage for cyclic to throttle mixing with many radio systems, it will be necessary to make any adjustment in the throttle travel limits by mechanical means only. Move the control linkage in or out on the servo/throttle arms until the correct barrel travel is achieved. Please note that it is very important the ATV (travel volume) for both the high and low throttle setting remain at their maximum values to prevent over-travel and binding of the throttle linkage when cyclic to throttle mixing is used.

Note: The use of cyclic to throttle mixing is recommended only for use by experienced pilots.

For initial cyclic to throttle mixing value information, please refer to the JR PCM10 series data sheets located on page 54 of this manual. Please note that the values and mixing channels shown are universal to most radio systems currently available.

### Cyclic to Throitie Channel and Mixing Values (most systems)

Mix #1	Chann	ėl	<u>Mixina</u>	Value
IVIIA # I	Master	<u>Slave</u> Throttle (1)*	Left 30	Right 30
<u>Mix #2</u>	<u>Master</u>	<u>Slave</u>	<u>Սք</u> 30	<u>Down</u> 30
Mix #3	Elevator(3)* (Optional)	Throttle (1)*	<u>Left</u> 20	Right 25
.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	<u>Master</u> Rudder(2)	<u>Slave</u> Throttie (1)*		

<sup>\*</sup>Numbers shown correspond with the correct JR channel numbers

#### Mixing Value Adjustment

Please note that it will be necessary to determine if the desired mixing values need to be a + or - value based on servo direction, etc.

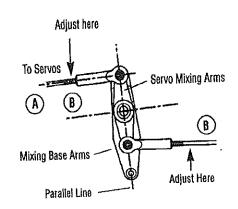
To verify the proper direction, move the control surface in each direction while watching the throttle arm. Throttle should increase each time a control surface input is given. Adjust the + or - value as necessary until the proper mix is achieved.

Note: Also check to confirm that the throttle travel is correct and is not causing a bind in the control linkage after the cyclic mixing has been added.

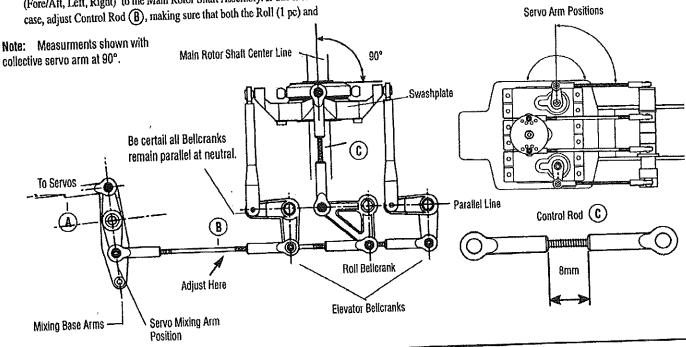
# CONTROL LEVER/LINKAGE ADJUSTMENT

Note: The following adjustments are made with all servos in the center (1/2 stick) or neutral positions.

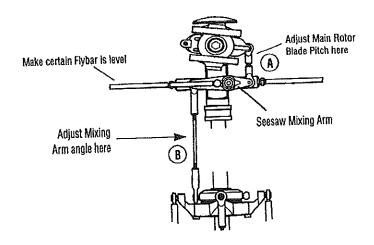
Check to insure that both the Elevator (2) and Aileron (1)
 Servo Mixing Arms are parallel (same angle) to the Mixing
 Base Arms (2) with all servos in the neutral (center) positions.
 If these items are not parallel, re-adjust the (A) and (B)
 Control Rods equally until proper alignment is acheived.



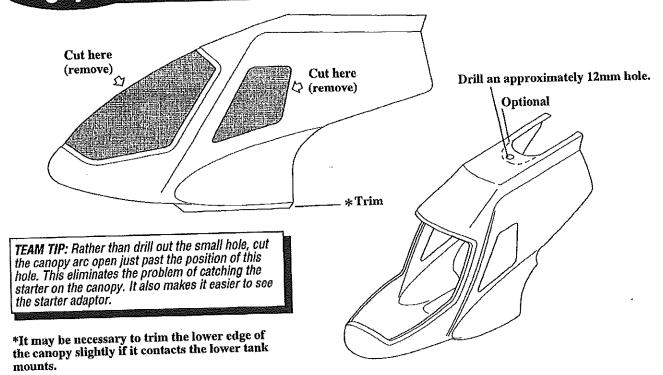
 Next, check to be sure the Swashplate Assembly is at 90° in all directions (Fore/Aft, Left, Right) to the Main Rotor Shaft Assembly. If this is not the case, adjust Control Rod (B), making sure that both the Roll (1 pc) and Elevator (2 pcs) Belicranks remain positioned parallel as shown. Also check to insure that control rod (c) is sized 8mm as shown below.



3. Check the Seesaw Mixing Arms (2) and adjust so that with the Flybar Assembly Level, and the Pitch at 1/2 stick (center), the Mixing Arms are level (parallel) as shown. If this is not the case, adjust the Control Rod (B) (2) until this positioning is achieved. Adjustment of the Main Rotor Blade Pitch to the desired settings can be achieved by using Control Rod (A) for adjustment. See page 36 Section 7-3 for Pitch range settings.

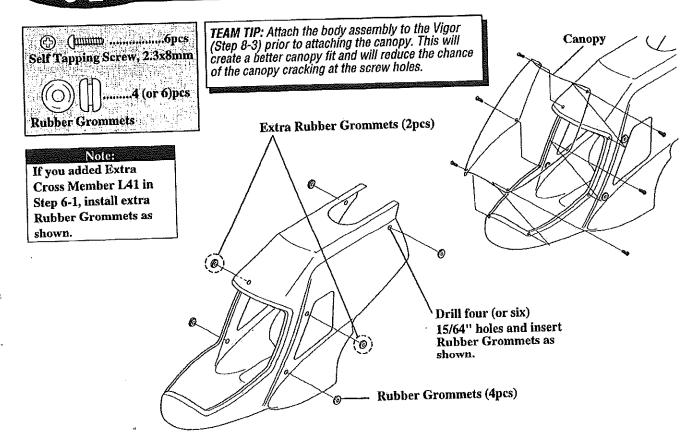


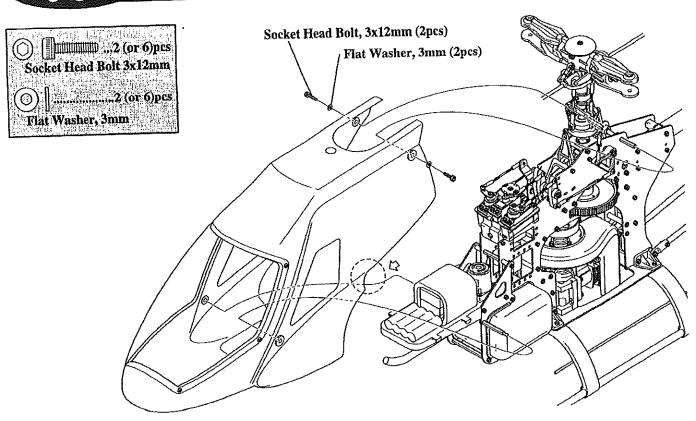
### TRIMMING OF BODY ASSEMBLY/CANOPY



8-2

# **BODY ASSEMBLY/CANOPY ATTACHMENT**



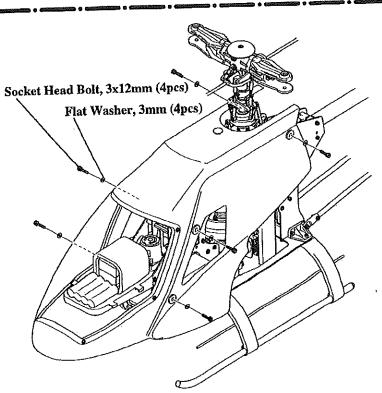


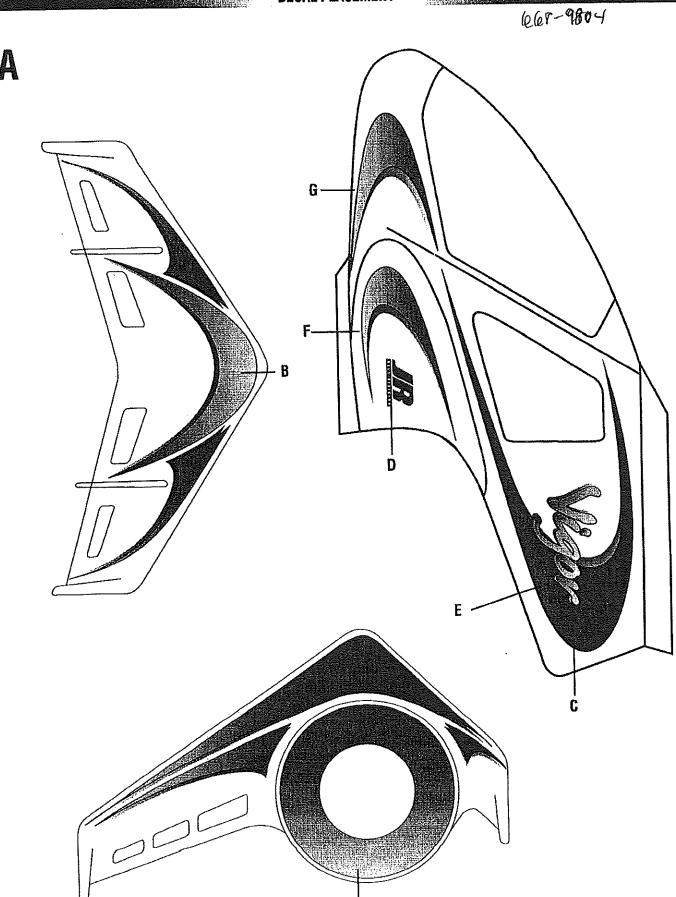
Check to insure the Body does not come in contact with any portion of the Main Frame, Muffler, Servo, Servo Horns, etc. Trim for clearance if necessary. Trim and remove a small portion of the canopy shown in the circle above as it is very close to the Cooling Fan Shroud (left side only).

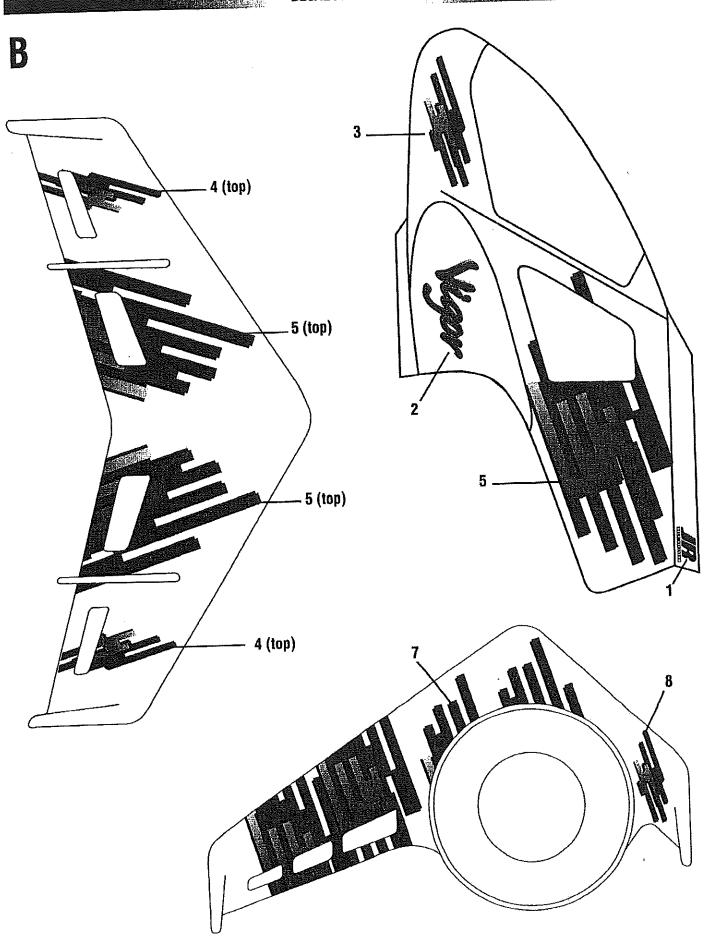
#### Note:

If you added Extra
Cross Member 41, and
changed the Cross
Member to the Extra
Cross Member 32 in
Step 6-1, you can attach
the Body at six places
with socket sead screws
as shown.

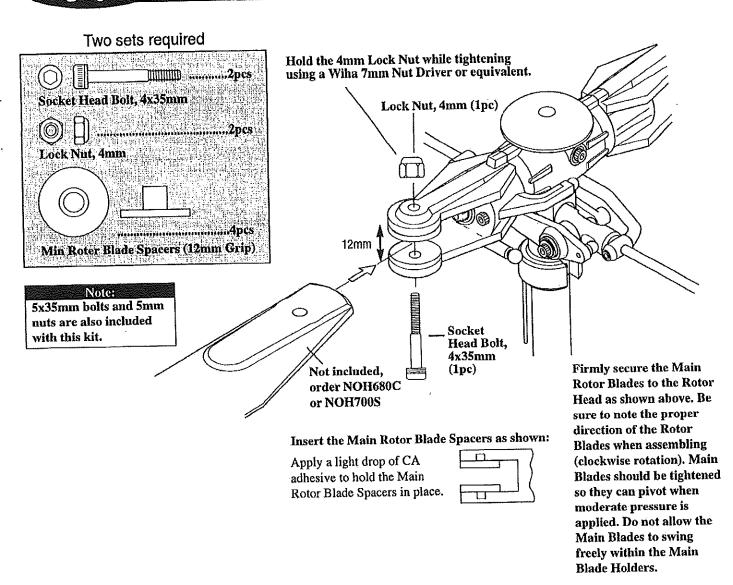
It is suggested that the body decals be applied at this time. Prior to decal attachment, clean the body using rubbing alcohol or lacquer thinner. If using lacquer thinner, make sure it doesn't come in contact with the canopy as it will damage this material.





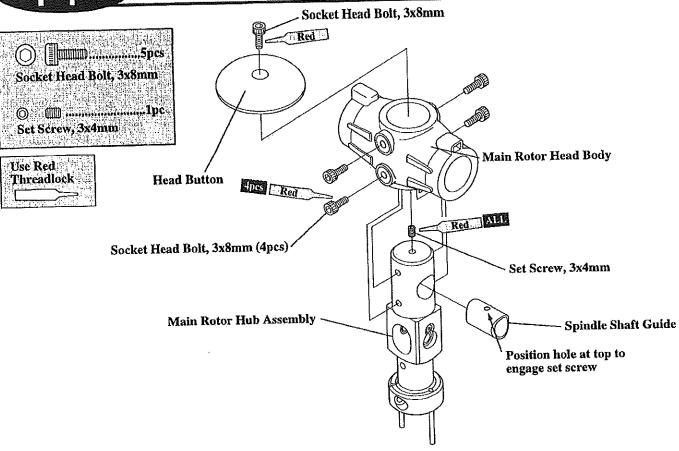


# MAIN ROTOR BLADE ATTACHMENT (BLADES NOT INCLUDED)



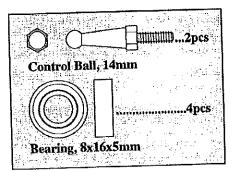
P-1

# **ASSEMBLY PROCESS - MAIN ROTOR HEAD 1**



P-2

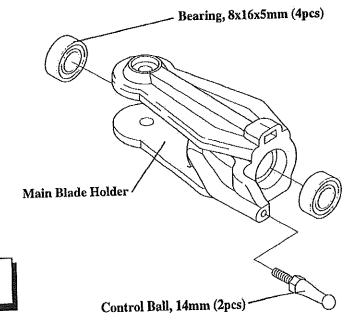
### **ASSEMBLY PROCESS – MAIN ROTOR HEAD 2**



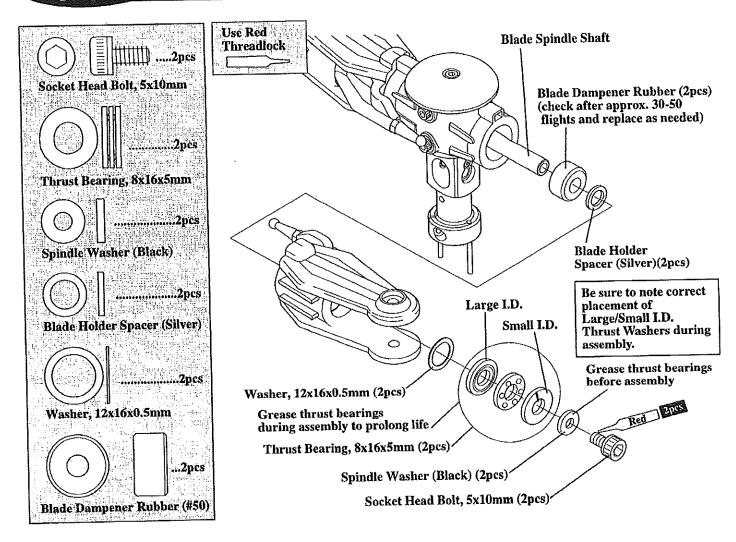
Use caution when inserting the Main Blade Holder Bearings so as not to distort/damage the Main Blade Holders.

Make two Main Blade Holders.

TEAM TIP: JB Weld the bearings into the blade holders to reduce play in the blade holders.

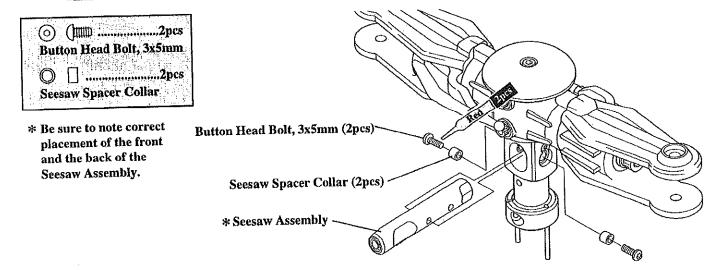


# ASSEMBLY PROCESS PARTS - MAIN ROTOR HEAD 3

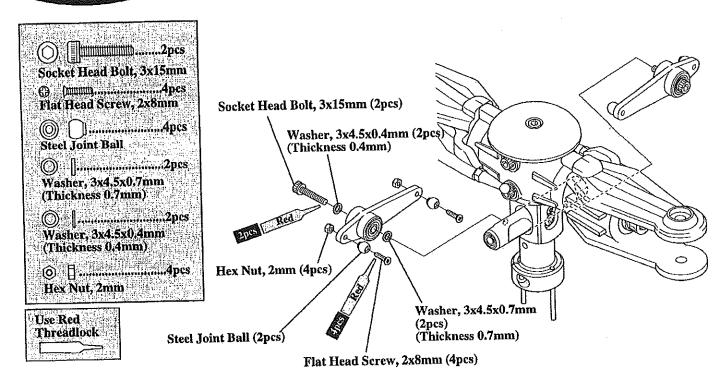


# P-4

### **ASSEMBLY PROCESS - MAIN ROTOR HEAD 4**



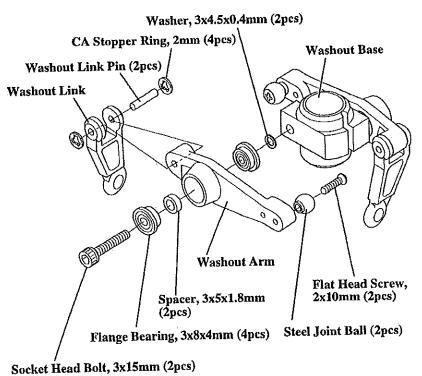
### **ASSEMBLY PROCESS - MAIN ROTOR HEAD 5**



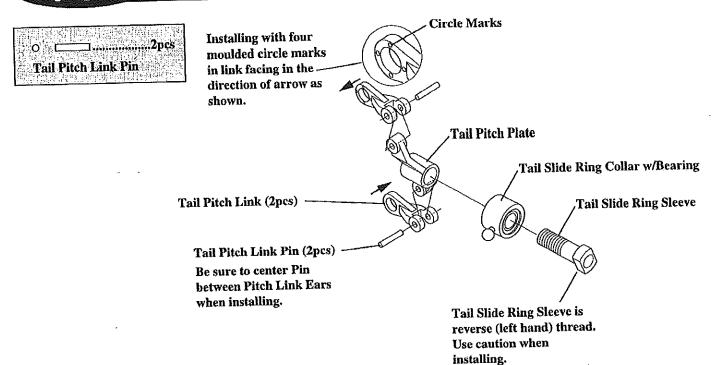
### PAG

### **ASSEMBLY PROCESS – WASHOUT UNIT**





# ASSEMBLY PROCESS - TAIL SLIDE RING



P-8

# ASSEMBLY PROCESS - FLYBAR CONTROL ARM

Red E	<b>— раше2рс</b> я
Flat Head Screw, 2x8mm (2pcs)	Flat Head Screw, 2x8mm
Steel Joint Ball (2pcs)	Steel Joint Ball
Flybar Control Arm	

Make two Flybar Control Arms.

Use Red Threadlock

# FINAL SERVO ADJUSTMENT AND RADIO SET-UP

Now that the radio system is completely installed into the helicopter, it's necessary to check and adjust the following:

### Servo Direction (Servo Reversing)

Check to insure that all servos have been set to the correct direction as shown in the Control Linkage Installation Section (Steps 7-1 to 7-5).

#### **Dual Rates**

It's suggested that for initial flights, the Dual Rate Function values be set as follows:

O Position (low rate) 70% 1 Position (high rate) 100%

#### **Exponential Settings**

It's suggested that the exponential rate settings remain in the 0 value position until the initial test flights. After initial flights, adjust the exponential values to achieve the desired control feel.

#### **Sub-Trim Settings**

It's suggested that the correct neutral settings be achieved without the use of the Sub-Trim Function. If sub-trim is used for final flight adjustments, the sub-trim values should not exceed 10. If the sub-trim values are greater, readjust the control linkages or servo arms and reset the sub-trims to 0.

### Travel Adjustment

The Travel Adjustment Function allows the control surface to be adjusted to achieve maximum travel or surface deflection. When using this feature, it's extremely important that the high/low, up/down values for each channel be set at an equal value or a differential movement will occur (Diagram B). It is especially important the throttle and collective pitch travel limits are set to an equal value (Diagram A).

Please refer to the diagrams below for clarification.

#### Incorrect Correct B A 100 100 50 50 50 50 100 10 Non-Linear Servo Travel Straight & Linear Servo Travel

### Pitch/Throttle Curve Adjustment

It is very important the throttle and pitch curves are adjusted properly to achieve the best performance from your helicopter. When properly adjusted, the main rotor head rpm should remain consistent throughout all maneuvers and throttle stick positions. A constant rpm will also help to improve the effectiveness and accuracy of the tail rotor and gyro systems.

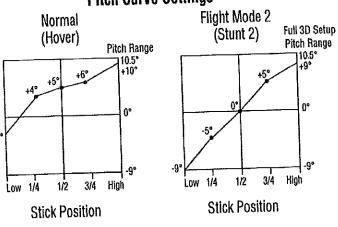
#### Pitch Curve Adjustment

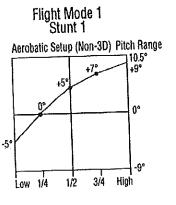
Using a pitch gauge (optional) set the low, mid and high stick pitch settings as shown in the diagram below. Use the Travel Adjust Function to set the maximum high and low pitch required for all flight modes. This pitch travel can then be reduced by altering the pitch curves as shown below.

### **Pitch Range Settings**

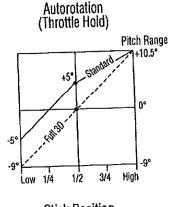
Flight Mode	Application	Low Pitch (Low Stick)	Hovering Pitch (Half Stick)	High Pitch (High Stick)
	Hovering	-2°	+5°	+10°
<del>"</del> -	Stunt & Aerobatic Flight	-5°	+5°	+9°
*2	3D Flight	-9°	0°	9°
<u>-</u> -	Autorotation	-5°	+5°	10.5°

### **Pitch Curve Settings**





Stick Position



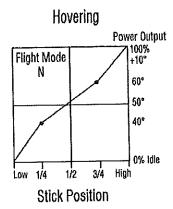
Stick Position

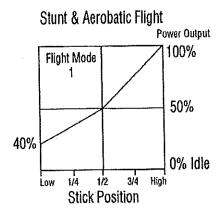
-3

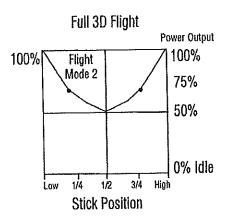
#### B. Throttle Curve Settings

Below are several examples of possible throttle curves during various flight conditions.

Since throttle curves can vary greatly due to engine and muffler combinations, it will be necessary to fine tune and adjust these values during test flights to achieve a constant main rotor rpm.







Note:

The throttle curve examples shown correspond to the pitch curve examples show in Step 6A on the previous page.

It will also be necessary to set the correct idle speed of the engine when the Throttle Hold Function is activated.

This idle value is located within the Throttle Hold Function. This will allow the engine to remain at idle when practicing autorotations.

#### 7. Revolution Mixing

It will be necessary to adjust the revolution mixing to properly compensate for the torque of the engine during all flight conditions (except autorotation).

Since there are many variables that can alter the value of the revolution mixing (engine, blade pitch, fuel, etc.), it will be necessary to fine tune this function during test flights.

The following values are shown only as a starting point toward achieving proper compensation:

Flight Mode N	Flight Mode 1	Flight Mode 2 (3D)
Up 40	Up 15	Up 15
Down 20	Down 10	Down 15

#### 8. Gyro Gain Adjustment

It will be necessary to adjust the "gain" or compensation of the gyro to create the correct amount of "holding power" necessary for a solid

neutral tail rotor. The intent of the gyro is to compensate for abrupt movements, or wind direction changes, working in conjunction with the Revolution Mixing Function.

For hovering, it's recommended that you start with the gyro gain at approximately 80° and continue to increase slightly until the tail of the helicopter "hunts," then reduce the value slightly.

This same adjustment will also be necessary to achieve proper forward flight. Generally, the gyro gain for forward flight will be approximately 10%-20% less than that of the established hover gain due to aerodynamic forces present in forward flight. This variance depends greatly on the specific gyro used.

If you are using a dual rate gyro, adjust the gain so you are using the "higher" gain setting for hover and the "lower" gain setting for forward flight.

#### **Gyro Direction**

It will also be necessary to confirm the direction the gyro compensates when the body of the helicopter is rotated.

To do this, turn the radio system on and suspend the helicopter by the main rotor head. Next, move the rudder stick to the right and watch the direction that the tail rotor servo arm travels. Now while watching the tail rotor servo arm, rotate the body of the helicopter counterclockwise. The servo arm should move in the same direction as when the rudder stick was moved to the left.

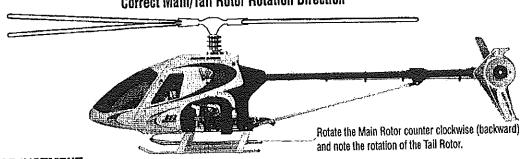
If the arm moves in the opposite direction, reverse the gyro and re-test.

#### FINAL PRE-FLIGHT CHECK

Once all assemblies have been completed, please review the following suggestions before attempting initial flights.

- Review the instruction book and confirm that all assembly steps have been completed thoroughly.
- Check to verify that the tail rotor assembly rotates in the correct direction (see the diagram below).
- Check to insure that all servos are operating smoothly and in the correct direction. Also verify that there is no binding in the control rods
- and that each servo horn is secured with a servo horn mounting screw.
- Verify that the gyro is operational and compensating in the correct direction (detailed in Step 6-5, page 33).
- Make sure that both the transmitter and receiver have been fully charged (refer to your radio system instructions for proper charging procedures).
- Check to insure that the throttle is working properly and in the correct direction.

### Correct Main/Tail Rotor Rotation Direction



### **BLADE TRACKING ADJUSTMENT**

Blade "tracking" is an adjustment to the main rotor blade pitch that must be accomplished during the initial test flights.

Although the blade pitch angle in each blade may appear equal, it is still possible for a set of main rotor blades to run "out of track," making adjustment necessary.

Main rotor blades that are out of track with one another can cause vibration, instability, and a loss of power due to additional drag.

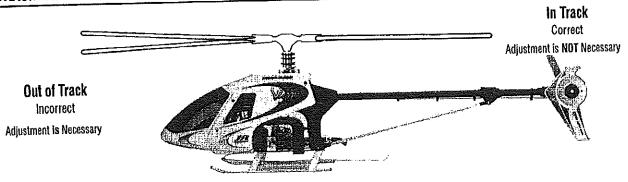
On the initial flight, it will be necessary to increase the blade speed to just before

lift-off rpm and view the rotor disc at eye level from a safe distance (approximately 15 to 20 feet).

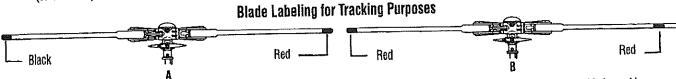
Note which blade is running low (by colored tracking tape) and increase the pitch of the low blade one turn of the ball link at a time until each blade runs in track (on the same plane).

Please refer to the diagrams below to identify the different tracking situations, as well as several methods to mark each rotor blade for tracking identification.

### **BLADE TRACKING IDENTIFICATION**



Caution: Be sure to maintain a safe distance from the helicopter (15 to 20 feet) when tracking main rotor blades.



- A: Use two different blade tracking tape colors (e.g., black and red) at the tip of each main rotor blade.
- B: Use the same color blade tracking tape located at different positions on each rotor blade.

Note: Adding additional blade tracking tape to the rotor blades at this stage will make it necessary to re-static balance the main rotor blades.

#### **GENERAL MAINTENANCE**

#### Engine

After each day of flying, fully drain the fuel tank. Then start the engine and let it idle until the engine and the fuel line are completely burned off. It is also suggested that an after-run oil be used to prevent premature engine corrosion.

#### Tail Rotor Belt

Periodically check the tension on the Tail Drive Belt (as shown in Step 5-6, page 28) to insure that it has sufficient tension for proper engagement. It is especially important to check this after initial test flights, and if a drastic temperature change has occurred from when the belt tension was originally set.

#### Check All Nuts and Bolts

A helicopter is subject to high vibration during flight. It is important to check that all screws, nuts and bolts are properly secured after each day of flying. It is also suggested that you perform a "quick" inspection between each initial test flight for approximately the first 6 to 10 flights.

#### Main Rotor Head

It will be necessary for the main rotor head dampners to be checked/and or replaced every 30-50 flights to maintain maximum rotor head performance. When replacing the main rotor head dampners, apply a light coating of oil to the dampners to prolong life.

It is also suggested at this time that the rotor head thrust bearings be lubricated using a high speed grease. This will prolong the visibility of the thrust bearings.

#### Washout Base

Lubricate the washout base using light oil every 10-15 flights to insure smooth operating and reduce wear. Inspect the washout base every 50-75 flights. If excess wear is noted, replace as needed.

#### Tail Pitch Slider

Lubricate the tail pitch slider using light oil every 10-15 flights to insure smooth operation and reduce wear.

#### Check Ball Link Wear

Check to insure that all universal links fit freely but securely to the control balls. If there is excessive play noted, adjust and or replace the universal link in question.

#### **Battery Maintenance**

Check to insure that your batteries are properly mounted and charged. The most frequent cause of crashes (aside from pilot error) is battery failure or disconnection. Be certain that your batteries are fully charged and limit your flight time to 3 or 4 flights between charging. If more flight time is required, purchase a reliable quick field charger.

#### Cleaning

At the end of each flight or flying session, wipe down your helicopter with a clean towel or rag. This is also a good time to inspect all parts for tightness or fatigue. Remember, a clean, well-maintained helicopter will provide you with many hours of trouble-free flight.

# XP8103 DATA SHEET HELI

MODEL NO. \_\_ MODEL NAME VIGOR 3D/JR G450 GYRO MODULATION SPCM - ZPCM - PPM \_

			AILE	ELEV	RUDD
DUALRATE • EXP		D/R	90%	90%	90%
	0	EXP	+25%	+25%	+30%
	1	D/R	100%	100%	100%
		EXP	+30%	+30%	+30%

AUTO	ST1	INH • (ACT)
D/R (POS. 1)	ST2	INH • (AC)
	ST2	INH • ACT

INPUT	AUX2	HOLD SW+ PIT,TRIM+INH		
SEL	GEAR	ACT • INH		

Ī		THRO		AILE		ELEV	R	UDD	(	SEAR		PIT	AUX2	Ä	UX3
**	REVERSE SW	NORA		NORM) REV	Œ	NORM) REV		ORM REV)	•	IORM) REV		IORM REV	NORAM REV	_	ORM) REV
	SUB-TRIM					ADJUST	SO	THAT N	O TR	IM IS REC	QUIR	ED			
		Н	150%	L 110%	D	110%	l.	150%	+	-%	Н	140%	+ 100%	+	100%
Throttle travel ————————————————————————————————————	TRAVEL ADJUST	L	150%	R 110%	U	110%	R	150%	-	-%	L	140%	- 100%	٠	100%
150% if program mixing is to be	FAIL SAFE (SPCM)						<u> </u>				<u> </u>				

must be set to	- IKAVEL	AUJU	131	L 150	)% R	110%	U 11	10%   F	150%	%	
150% if program mixing is to be used.	FAIL SAF	E (SPO	CM)								1
0360.			EXP	L		1	2		3	Н	
		Ν	OFF OF	0%	, l	40%	4	50%	60%	100%	ļ
*	THROTTLE CURVE	1	OFF (O	40'	%	50%				100%	-
	·	2	OFF (O	100	)%	75%	,	60%	75%	100%	1
		Z	OFF (O	3	٠	+4°		+5°	+6°	+10°	
*	PITCH	,	OFF (O	N) -5	ò	0°		+5°	+7°	+9°	4
	CURVE	2	OFF (O	N) -9		-5°		0°	+5°	+9"	_
		Н	OFF (O	N) -5		+5°				+10.5°	ا '

		0		%
GYRO	INH RUDD D/R AUTO	1		%
SENS		Ŋ	ORM	
		S	TNT	
		Н	OLD	
	ļ		NVT	

		POS
THRO HOLD	INH • (ACT)	16%

TURO HOLD	(NH) • ACT	OFFSET
THRO HOLD	NH) • ACI	%

LIODELLE.	UP	40°
NORMAL	DOWN	20°
071117	UP	15°
SIUNI	DOWN	15°
	NORMAL	DOWN UP

			CLAZ	EXP	-	1	2	3	Н
		CHANNEL	SW						30
	MIX1	AILE→THRO	ON	OFF-ON)	30		0		
PROGRAM	MIX2	ELEV→THRO	ON	OFF-(DN)	30	-	0		30
WIX				+POS		-PO	S	OFF	SET
:	WIX3	RUDD→THRO		30%		30	)%	0	

# Data Sheets POWIOSXII

MODEL NO. (84) \_\_\_\_\_

MODEL NAME (81) \_JR Vigor 3D/JRG450 Gyro

MODULATION (85) SPCM-ZPCM-PPM

		THRO		AILE			ELEV			RUDD	)		GEAF	<b>}</b>		PITCH	ł		AUX2	!		AUX3	3		AUX4			AUX	š
REVERSE SW (11)		®		R	****		R			®			R			R			R (N)	•		R (N)			R (N)			R	
TRAVEL ADJUST	Н	%	L	110	%	D	110	%	L	150	%	+		%	+	140	%	+		%	+		%	4		%	+	_	%
(12)	L	%	R	110	%	U	110	%	R	150	%	-	•	%		140	%	-		%	-		%	-		%	-		%
SUB-TRIM (15)			<b></b>			1					A	djus	t so th	nat n	o trir	n is re	quin	ed											
TRIM RATE (83)		50 %		100	) %	Π	100	) %		100	%	Г																	

			AILE	ELEV	RUDD
VII		D/R	90 %	90 %	90 %
	0	EXP	+25%	+25%	+30%
		TYPE			
D/R		D/R	100 %	100 %	100 %
EXP	1	EXP	+30 %	+30 %	+30 %
(13)		TYPE			
		D/R	%	%	%
	2	EXP	%	%	%
		TYPE			
	ST-1	INHACT	0 1 2	0 1 2	0 1 2
AUTO	ST-2	INHACT	0 1 2	0 (1) 2	0①2
D/R	ST-3	INH-ACT	0 - 1 - 2	0 · 1 · 2	0 - 1 - 2
(23)	ST-4	INH-ACT	0-1-2	0.1.2	0 - 1 - 2
	HOLD	INHACD	0 1 2	0 1 2	0 1 2
	ST-1	INHACT	Adinet se n	ecessary duri	na fliaht
STUNT	ST-2	INHACT		ooooony don	
TRIM	ST-3	INH·ACT			
(25)	ST-4	INH-ACT			
	HOLD	INHACT			

THROTTLE	HOLD SW	INH: HOLD
HOLD	POS	Adjust for Idle
(16)	AUTO GUT	(NH)ACT
		POS

	FLIG EXT		OH GEAR AILE
FUNCTION SELECT	GEA SV		<b>®</b> GEAR HOLD
(17)	AUX SV		(N)DACT
	PIT.	LOW	(NB)ACT
	LEVER	Н	(NH) ACT

			0		Ę	0	
GYRO	l inh		1		- 6	35	
SENS	AUX 3		2		f	35	
(44)	OTUA	NR	S1	S2	\$3	\$4	HD
		0	1	2			1

mids			CHANNE MASTER	SLAVE	TRIM	sw		OFFSE	Т		+G <i>l</i>	MN		_	GAIN	
<del>, , , , , , , , , , , , , , , , , , , </del>	1	INH AČT			OFF DN	NA:S1:S2:S3:S4 HD:AX2:GER										
	2	INH ACT	->		OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER										
	3	INH ACT	->		OFF ON	NR:S1:S2:S3:S4 HD:AX2:GER										
	4	INH ACT	->		OFF ON	NR+S1+S2+S3+S4 HD+AX2+GER									,	
PROGRAM							EXP		F	1	5	3	4	5	6	H
MIX (51) - (58)	5	INH ACT	_	•	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER	OFF	IN OUT	0							100
	6	INH ACT		•	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER	OFF	IN OUT	0							100
	7	INH		·	OFF	NR•S1•S2•S3•S4 HD•AX2•GER	OFF ON	IN OUT	0							100
	8	INH ACT		<b>.</b>	OFF ON	NR+S1+S2+S3+S4 HO+AX2+GER	OFF ON	או זעס	0							100

			<del></del>	<del>-                                    </del>	1	2	3	4	5	6	<u>H</u>
		EXP			25	50	75				100
		OFF	IN	0	40	50	60				100
	N	<b>(0)</b>	OUT	0		HOV	HOV	НОУ	ноу	НОУ	
THRO			HOV.SEL		НОУ	nuv	1107	nov			100
l	1	OFF	IN	0	50						100
CURVE		(N)	OUT	40	50	50	75				100
(18)	2	OFF	1N	0	25	60	75	<u> </u>			100
rh,trim=slow		(N)	OUT	100	75	00	/3				100
HOV.T=CENTER	3	OFF	IN	0							
1104:1-02:1121		ON	OUT					<del> </del>	<u> </u>		100
	4	OFF	IN	0				<del>                                     </del>			<del>                                     </del>
	4	ON	OUT				75	<del>                                     </del>			100
		· OFF	IN IN	0	25	50	+6°	<u> </u>			+10°
	N	<b>(b)</b>	OUT	(-3°)	+4°	+5°	HOV	HOV	HOV	HOV	<del> </del>
			HOV.SEL		HOV	HOV		1100	1104		100
	1	OFF	IN	0	25	50	75 +7°				+9°
PITCH		ON	OUT	-5°	0°	+5°	75				100
CURVE	2	OFF	IN	0	25	50 0°	+5°				+9°
(68)		ON	OUT	-9°	-5°	\ <u>'</u>	1 10				100
• •	3	OFF	IN	0	<u> </u>	<del> </del>					
P,TRIM=CENTER		ON	OUT	<u> </u>	-				<u> </u>		100
HOV.P=CENTER	4	OFF	IN	0				1			
	<u> </u>	ON	OUT	<del> </del>	50						100
	HOL	d off	OUT	-5°	+5°						+10.5°
	1	עוט ו	1 001			<del> </del>					+10.5
10	HOL.	D)		-9°	0°	<u> </u>	1	<u> </u>	i	1	

	N	RIGHT	· LEFT U	IP	40%	DN	20	% H	OV. PO	S.	_
				L	1	2	3	4	5	6	Н
TAIL		NOR	IN	0	25	50	_		-	—	100
ROTOR CURVE	1	ORG	OUT	-8	-3	-8				<del>-</del>	-12
(47)		NOR	IN	0	25	50	75				100
• •	2	ORG	OUT	-12	-8	-3	-8	_	1	_	-12
	-	NOR	IN	0	<u> </u>	<del>                                     </del>					100
	3	ORG	OUT	T							
	<u> </u>	NOR	IN	0							100
	4	ORG	OUT								
STUNT MIX R	ATE	1/1	• 1/2	• @	<u>)                                     </u>	1/10					

L.									
_	TOM DEECET	-HV.T	HV.P	LO.P	HI.P	AILE	ELEV	RUDD	
	TRIM OFFSET (82)								

Rudder>Throttle	R	+30 %
4->1  -   MIX (41)	L	-30 %
MODE SELECTION	NR (\$) (\$2) 53 ·	\$4 • AX2

Alleron→Throttle	R	+30 %
2→1 MIX (41)	L	-30 %
MODE SELECTION	NR (\$) (\$2.53.54	· AX2

Elevator→Throttle	U	+30
3→1 MIX (41)	D	-30
MODE SELECTION	NR (S) (2) S3 · S	64 • AX2

FAIL-	T_1	MODE	HOLD • 1.0s • 0.5s • 0.25s
SAFE	4	MEMORY	
(77)	S	MEMORY	Throttle at 1/4 stick

PILOT LINK (78) INH · MST · SLV

	( SERV	(D)	3SERVO	- 120°C	CPM	
SWASHPLATE MIXING				D		0 %
TYPE (65)	-	ELE	→ AIL	U	0 %	
	1SERVO			L		0 %
		AIL	→ ELE	R		0%
	SWITCH	NP	· S1 · S	2 • 83 • 8	54 • HD	
3 SERVO 120° CCPM	AIL	%	ELE	%	PIT	%

# Dara Sheets 10X Heli

MODEL NO. (84)

MODEL NAME (81) JR Vigor 3D/JRG450 Gyro

MODULATION (85) SPCM-ZPCM-PPM

	T	HRO	Γ	AILE		Γ	ELEV	1	Γ	RUD	D		GEAF	₹		PITCH	1		AUX2			AUX	3		AUX-	1		AUX5	;
REVERSE SW (11)	R N			R (N)		R				(R) N			R (N)			® <sub>N</sub>		R (N)		R (N)		-	R		R (N)				
TRAVEL ADJUST	Н	%	L.	110	%	D	110	%	L	150	%	+	-	%	+	140	%	+		%	+	_	%	+	<u> </u>	%	+	_	%
(12)	L	%	R	110	%	U	110	%	R	150	%	-		%	-	140	%	-		%	_		%	-		%	-		%
SUB-TRIM (15)	Adje	ist so th	nat	no trim	is r	eqi	ired																						
TRIM RATE (83)		50 %	Π	4		Π	4			4		Γ																	

	······		AILE	ELEV	RUDD
		D/R	90 %	90 %	90 %
	0	EXP	+25 %	+25 %	+30 %
		TYPE			
D/R		D/R	100 %	100 %	100 %
EXP	1	EXP	+30 %	+30 %	+30 %
(13)		TYPE		-	
		D/R	%	%	%
	2	EXP	%	%	%
		TYPE			
	ST-1	INHACO	0 (1) 2	0 1 2	0 1 2
AUTO	ST-2	INHACT	0 1 2	0 1 2	0 1 2
D/R	ST-3	INH-ACT	0 - 1 - 2	0 · 1 · 2	0-1-2
(23)	ST-4	INH-ACT	0-1-2	0 • 1 • 2	0 · 1 · 2
	HOLD	INHACT	0 1 2	0 1 2	0 1 2

THROTTLE	HOLD SW	INH GEAR
HOLO	POS	Adjust for idle
(16)	AUTO CUT	(INH)ACT
		POS
	Delay	1/4 1/2 (3/4) 1

	FLIG EXTI		(NH) GEAR AILE
FUNCTION SELECT	GEA SW		(NH) GEAR HOLD
(17)	KUA VS		(NH)ACT
	PIT.	LOW	(NH)ACT
	LEVER	н	(INH)ACT
	ADT STU	NT	INH(ACT)

		Ī	0	Т	90					
GYRO SENS	INH AUX 3		1	_	65 65					
(44)	AUTO	NR	<u> </u>	S2	S3		HD			
•		0	1	2			1			

			CHANN MASTER	EL SLAVE	TRIM	SW		OFFSE	īΤ		+G/	AIN.		-	GAIN	
	1	INH ACT		·	OFF ON	NR-81-82-83-84 HD-AX2-GER										
	2	INH AČT	-		OFF ON	NR+S1+S2+S3+S4 HD+AX2+GER										
	3	INH AČT		•	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER						,,,,				
	4	INH AČT		·	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER										
PROGRAM							EXP		L	-1	2	3	4	5	6	н
MIX (51) - (58)	5	INH ACT		•	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER	OFF ON	IN OUT	0							100
	6	INH ACT	_	<b>&gt;</b>	OFF ON	NR·S1·S2·S3·S4 HD·AX2·GER	OFF ON	IN OUT	0							100
	7	INH	_	<b>&gt;</b>	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER	OFF	IN OUT	0							100
	8	INH ACT	_	<b>&gt;</b>	OFF ON	NR-S1-S2-S3-S4 HD-AX2-GER	OFF ON	и ОUT	0							100

	<del></del>		Т		1 1	2	3	4	5	6	H
		EXP			25	50	75				100
1	1	OFF	1N	0	40	50	60				100
	N	<b>(M)</b>	OUT	0			HOV	НОУ	ноν	HOV	
TUDO [		<b></b>	HOV.SEL		HOV	ноν	nuv	nov	1101		100
THRO	1	OFF	lN	0	50						100
CURVE		(i)	OUT	40	50		75				100
(18)	2	OFF	IN I	0	25	50	75				100
rh,trim=slow	2	(A)	OUT	100	75	60	10				100
HOV.T=CENTER	3	OFF	IN	0							
HOV. I=OCNILII	3	ON	OUT								100
	4	OFF	IN	0					<del> </del>		
	4	ON	OUT				7,-	<del> </del>			100
		٥٢٢	IN	0	25	50	75				+10°
	N	OFF	OUT	-3°	+4°	+5°	+6°	11007	HOV	НОУ	<del>                                     </del>
		(N)	HOV.SEL		HOV	HOV	YOV	HOV	nuv	1104	100
	<u> </u>	OFF	IN	0	25	50	75	<del></del>			+9°
PITCH	1	ON	OUT	•5°	0°	+5°	+7°				100
CURVE		OFF	IN	0	25	50	75				+9°
	2	ON	OUT	-9°	-5°	0°	+5°				100
(68)		OFF	IN	0							1
P,TRIM=CENTER	3	ON	OUT		<u> </u>	<u> </u>					100
HOV.P=CENTER	4	OFF	IN	0		<del> </del>	<del> </del>				
	4	ON	OUT			<del>                                     </del>					100
	HOL	N OFF		0	50						+10.5
	1	עוש ן	OUT	-5°	+5*						+10.5
OT	HOL	'n		-9°	0°			_1			1 +10.52

<u> </u>	T	NOR	IN	L	1	2	3	4	5	6	Н
	N	ORG	OUT	+5	+3						-3.
TAIL	$\vdash$	NOR	IN	0	25	50	75				100
ROTOR CURVE	1	ORG	OUT	-8	-3	-8	_				-12
(47)	<u> </u>	NOR	IN	0	25	50	75		-		100
Ç <i>y</i>	2	ORG	OUT	-12	-8	-3	-8				-12
	-	NOR	IN	0							100
	3	ORG	OUT	1				Ī			<u> </u>
	-	NOR	IN	0	1	T -		T			100
	4	ORG	OUT								<u> </u>
MIX RATE	1	1/1	• 1/2	• (/	<u>) · </u>	1/10					

Note: Omit Tail Rotor Curve if Heading Lock/Tail Lock Gyro is used (all output values 0)

TRIM OFFSET	HV.T	ну.Р	LO.P	HI.P
(82)	<u> </u>			

Rudder→Throttle	R	+30 %
4→1 MIX (41)	L	-30 %
MODE SELECTION	NR (S1)(S2) S3 ·	S4 - AX2

FAIL-	1,	MODE	HOLD - 1.0s - 0.5s - 0.25s
SAFE	12	MEMORY	
(77)	S	MEMORY	Throttle at 1/4 stick

Aileron→Throttle	R	+30 %
2→1 MIX (41)	L	-30 %
MODE SELECTION	NR (S1)(S2) S3 · S	54 • AX2

Elevator→Throttle	U	+30
3→1 MIX (41)	D	-30
MODE SELECTION	NR (\$1)(\$2)-\$3 -\$4	•AX2

,	(1 SERV	(SERVO - 3SERVO - 120°CCPM - 3SERVO -					40°CCPM
SWASHPLATE		ELE → AIL		D			0 %
MIXING TYPE (65)	1SERVO			Ü			0 %
			╗	L			0 %
* •		AIL → ELE		R			0 %
	SWITCH	NR - S1	٠S	2 - \$3 -	S4 · HD		
3 SERVO 120° CCPM	AIL.	%	E	LE	%	PIT	%
3 SERVO 140° CCPM	AIL	%	E	LE	%	PIT	%

#### Main Rotor Head/ Swashplate/ Washout Assembly JRP996020 (Red) JRP980004 KSJ99330 (Grey) JRP970069 JRP994008 JRP960189 JRP980018 PPIOOP JRP960180 Ø JRP980040 JRP970001 JRP960179 JRP980004 JRP960288 (Hardness #50) JRP960195 JRP980013 JRP970175 JRP993001 (610mm) JRP970098 JRP\$65001 (450mm) JRP970098 JRP994005 JRP960176 JRP994005 JRP980001 **CIMINIMIN** JRP980052 JRP980052 JRP996027 JRP994007 JRP960258 JRP970115 JRP996026 JRP960178B JRP980039 (Optional) JRP970001 JRP970082 GOMO. JRP980037 JRP980075 (**(**)) JRP980016 (5mm) JRP980030 JRP970029 JRP970099 JRP970077 JRP996028 JRP981027 JRP980015 JRP970093 JRP970010 JRP970082 JRP960013 JRP970004 JRP980074 JRP981026 JRP98005 JRP981015 JRP980042 JRP970004 JRP960249 JRP970002 JRP980016 Blade Dampner Rubber NO OFFICE JRP960573: Hardness # 45 JRP970004 JRP981031 JRP970119 OPTION JRP970078 JRP980042 JRP970002 JRP970001 JRP960202 JRP996012 · JRP996021

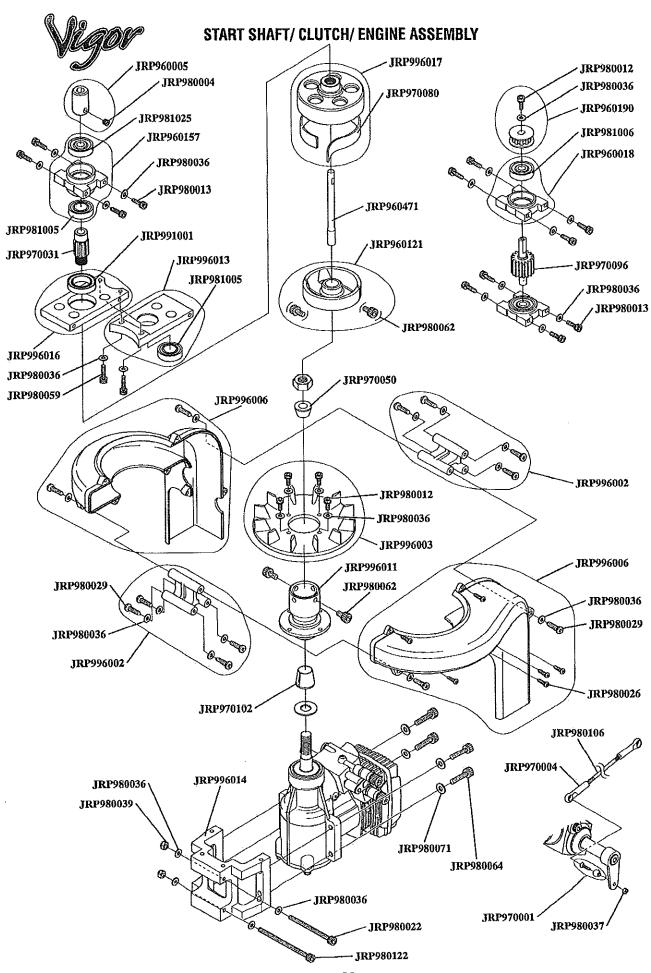
### VIGOR MANUAL PARTS LISTINGS Main Rotor Head/ Swashplate/ Washout Assembly

Part #	Description (	Quantity	Comments/ Additional Contents
	Socket Head Bolt, 3x8mm	10	
980013	Set Screw, 4x4mm	10	
980004	Elevator Arm, Front	1	Complete w/all Hardware
996020	Flybar Weights	2	Complete w/Set Screws
994008	Head Button	1	Complete w/one 3x8mm Socket Head Bolts
960189		i	Complete w/two 5x10mm Socket Head Bolts
960180	Blade Spindle Shaft	10	Complete w/ten 2x8mm Screws
970001	Steel Joint Ball w/2x8mm Screw	10	<b>44.11.</b>
980040	Nylon Lock Nut, 4mm	2	Complete w/Steel Joint Ball and Screws
960179	Flybar Control Arm	2	
960288	Blade Dampeners, 50	ī	Complete w/four 3x8mm Socket Head Bolts
960195	Main Rotor Body	10	
970098	Universal Ball Link (short)	2	
994005	Control Ball, 14mm	2	
960176	Blade Holder Spacer	10	
980001	Set Screw, 3x4mm	2	
980052	Control Rod, 2.3x15mm	1	Complete w/all Hardware
960258	Seesaw Mixing Arm Assm. w/BB		Hardware not included
960178B	Seesaw Mixing Arm w/BB (23) (optional)	10	
980039	Nylon Lock Nut, 3mm Low Profile	1	
994007	Spindle Shaft Guide	10	
970115	Washer, .03x4.5x0.7	2	Complete w/two 14mm Control Balls
996026	Main Blade Holder	10	- · · · ·
970082	Washer, .03x4.5x0.4	10	
980037	Hex nut, 2mm	10	
980030	Button Head Bolt, 3x5mm	2	Complete w/two 4mm Bolts, and 12mm Grip Spacers
970069	Blade Bolts w/Spacers	10	<b>V</b>
980075	Nylon Lock Nut. 5mm	10	
980016	Socket Head Bolt, 3x15mm	2	
970029	Seesaw Spacer Collar	2	Complete w/two Lock Nuts and Washers
970077	Main Rotor Shaft Bolt, 3x22mm	1	Complete w/all Hardware
996028	Seesaw Shaft Assembly	2	Complete w/all Hardware
970010	Washout Link	10	2
981015	CA Stopper Ring	1 .	
960013	Washout Base	10	
970004	Universal Ball Link	2	
980053	Control Rod, 2.3x50mm	2	
980042	Control Rod, 2.3x30mm	2	
981026	Bearing, 8x16x5mm	2	
970099	Washer, 12x16x0.5mm	2	
981027	Thrust Bearing, 8x16x5mm	2	
970093	Spindle Shaft Washer	10	
980074	Socket Head Bolt, 5x10mm	2	
960573	Blade Dampeners, 45	1	Pre-assembled w/all Hardware
996021	Main Rotor Head Assembly, Complete	10	Complete w/ten 2x10mm screws
970002	Steel Joint Ball w/2x10mm Screw	1	Complete w/all Hardware
960249	Washout Arm W/BB	10	•
980016	Socket Head Bolt, 3x15mm	2	
981031	Bearing w/Flange, 3x8x4mm	2	
970119	Spacer, 3x5x1.8mm	2	
970078	Joint Ball Spacer, 2.75mm	1	Complete w/all Hardware
960202	Aluminum Swashplate Assembly	1	- anipress of the second
996012	Main Rotor Shaft	ı	

#### CYCLIC MIXING ARMS/AILERON/ELEVATOR CONTROL ARMS JRP980002 JRP960231 JRP980049 JRP960022 JRP960020 JRP970016 JRP980039 JRP970017 JRP980049 JRP970082 O. JRP981031 JRP960021 JRP970119 JRP980013 JRP970001 JRP981031 JRP980037 JRP970001 JRP960261 JRP980087 JRP960264 JRP980039 JRP980037 JRP970004 JRP980019 JRP970002 JRP970004 JRP980085 JRP980012 ~ JRP970004 JRP981030-JRP970115 JRP980056 JRP980050 JRP970115 JRP981031 JRP970115 JRP980045 JRP970121 JRP970115 JRP960265 JRP970018 JRP970004 JRP970002 JRP970004 JRP980121 JRP970019 JRP981031 JRP970001 0 JRP980037 PO JRP960263 JRP980037 -JRP970116 JRP980097 JRP980050 JRP960265 JRP970004 JRP980121 JRP970001 JRP980045 JRP970001 JRP996007 -JRP980037 JRP980027 JRP980035 JRP980039 JRP980026 -JRP980022 60

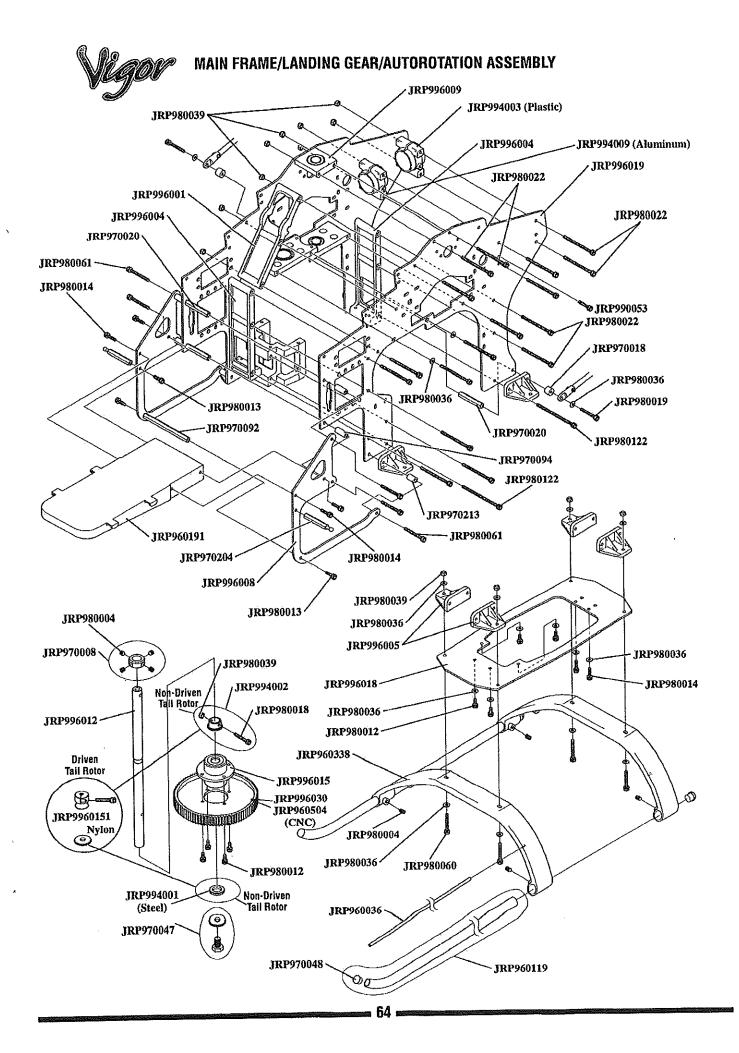
### VIGOR MANUAL PARTS LISTINGS Cyclic Mixing Arms/Aileron/Elevator Control Arms

	Cyclic mixing Arms/Anoton/2007200					
Part #	Description	Quantity	Comments/ Additional Contents			
*****	Elevator Arm: Front	1	Complete w/Bushing			
960020	Elevator Artii. 130110		Steel Joint Ball			
			2x8mm Flat Head Screw			
060001	Elevator Arm: Rear	1	Complete w/Bushing			
960021	Cigyator Arist. Flour		Steel Joint Ball			
			2x8mm Flat Head Screw			
000000	Swashplate A Arm	2	Complete w/two A-Arm Pins			
960022 996007	Upper Servo Tray	1	Complete w/all Hardware			
960261	Roll Bellcrank	1	Complete w/Bearings			
900201	Holt Desorativ		2 - Steel Joint Balls			
			2 - 2x8mm Flat Head Screws			
			2 - 2mm Hex Nuts			
960263	Mixing Base Arm: Roll	1	Complete w/Bearings			
960264	Mixing Base Arm: Collective	1	Complete w/Bearings			
00020.	***************************************		2 - Steel Joint Ball			
			2 - 2x8mm Flat Head Screw			
		_	2 - 2mm Hex Nut			
960265	Mixing Lever: Cyclic	3	Complete w/Bearings			
000	•		6 - Steel Joint Balls 6 - 2x8mm Flat Head Screws			
		40	6 - SXOIIIII LIGI LIGAR SOLEMS			
970001	Joint Ball w/2x8mm Screw	10				
970002	Steel Joint Ball w/2x10mm Screw	10				
960116	Mixing Base Nut	2	,			
970004	Universal Ball Link	10				
970016	Elevator Arm Bushing	2 2 2 1				
970017	Roll Belicrank Spacer	2				
970018	Mixing Lever Spacer	<u>ج</u> 1				
970019	Mixing Base Cross Member	10				
970082	Washer, 3x4.5x.4mm	2				
970115	Mixing Lever Bushing B	10				
970119	Spacer, 3x.5x1.8mm	10				
980012	Socket Head Bolt, 3x6mm Socket Head Bolt, 3x8mm	10				
980013	Socket Head Bolt, 3x22mm	10				
980019	Self Tapping Screw, 2.6x12mm	10				
980027	Flat Washer, 2.6mm	10				
980035	Hex Nut, 2mm	10				
980037	Control Rod, 2.3x45mm	2				
980045	Control Rod, 2.3x85mm	2				
980056 980050	Flat Head Screw, 3x8mm	10				
980085	Control Rod, 2.3x55mm	2				
980087	Control Rod, 2.3x120mm	2.				
981031	Bearing, Flanged, 3x8x4mm	2				
980121	Control Rod, 2.3x25mm	2				
980049	Nylon Washer, 5x8x0.5mm	10				
980039	Nylon Lock Nut, 3mm low profile	10				
980002	Set Screw, 3x18mm	10				
960231	Main Frame Standoff, 24mm	2				
981030	Bearing, Flanged, 5x8x2.5mm	1 2				
970121	Spacer, 3x5x1.8mm	∠ 5				
980097	Socket Head Bolt, 3x55mm	ง 10				
980026	Self Tapping Screw, 2.6x8mm	10				
980022	Socket Head Bolt, 3x40mm	10				



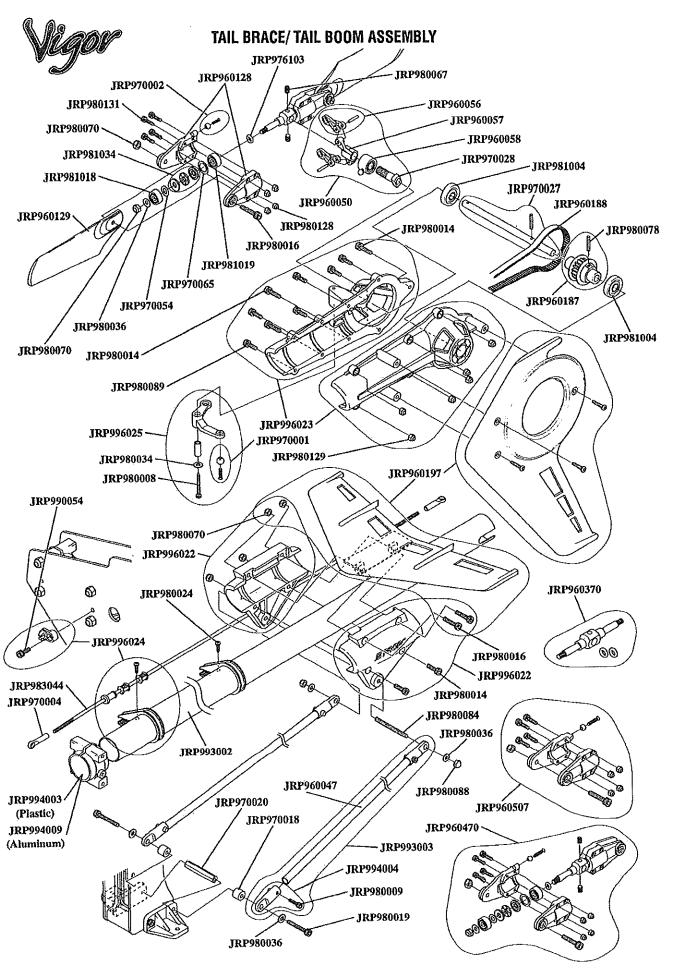
### VIGOR MANUAL PARTS LISTINGS Start Shaft/ Clutch/ Engine Assembly

Part #	Description	Quantity	Comments/ Additional Contents
LGILT	0000,000	_	Complete w/two 4x4mm Set Screws
960005	Hex Shaft Adaptor	1	Comblete Altwo avaiting our opions
980004	Set Screw, 4x4mm	10	
981025	Bearing, Sealed, 5x19x6mm	2	
960157	Start Shaft Bearing Block w/BB	1	
980036	Flat Washer, 3mm	10	
980013	Socket Head Bolt, 3x8mm	10	
996017	Clutch Bell Assembly w/BB	1	Complete w/Bearing & Clutch Lining
970080	Clutch Lining	1	
960471	Start Shaft	1	To the selection to One on Bolto
960121	Clutch Assembly	1	Complete w/two 4x6mm Bolts
980062	Socket Head Bolt, 4x6mm	10	
981005	Bail Bearing, 10x19x7mm	2	
970031	Pinion Gear, 9 Tooth	1	
991001	Ball Bearing, 15x24x5mm	1	
996013	Long Bearing Block "B"	1	Complete w/Bearing
996016	Long Bearing Block "A"	1	Complete w/Bearing
980059	Socket Head Bolt, 3x14mm	10	
980012	Socket Head Bolt, 3x6mm	10	(D. IS O Milankov
960190	Front Tail Belt Pulley	1	Complete w/Bolt & Washer
981006	Ball Bearing, 6x19x6mm	2	n I. I/Danving
960018	Bearing Block, Tail Pinion w/BB	1	Complete w/Bearing
970096	Tail Drive Pinion	1	
970050	Taper Collet "B", Upper	1	1-left, 1-right half Complete w/Screws
996006	Cooling Fan Shroud	1	Complete w/Screws and Washers
996002	Cooling Shroud Brackets	2	Complete Wacrews and Washers
996003	Cooling Fan Blades	1	Complete w/Screws and Washers
996011	Cooling Fan Hub	1	
980062	Socket Head Bolt, 4x6mm	10	
980029	Self Tapping Screw, 3x12mm	10	
970102	Taper Collet "C", Lower	1	
980039	Nylon Lack Nut, 3mm Low Profile	10	
996014	Engine Mount	1	
980022	Socket Head Bolt, 3x40mm	10	
980122	Socket Head Bolt, 3x50mm	10	
980071	Flat Washer, 4mm	10	
980064	Socket Head Bolt, 4x15mm	10	Complete w/ten 2x8mm Screws
970001	Steel Joint Ball w/2x8mm Screw	10	Complete witch System Colons
980037	Hex Nut, 2mm	10	
	Universal Ball Link	10	
970004	Universal Ball Link	10	



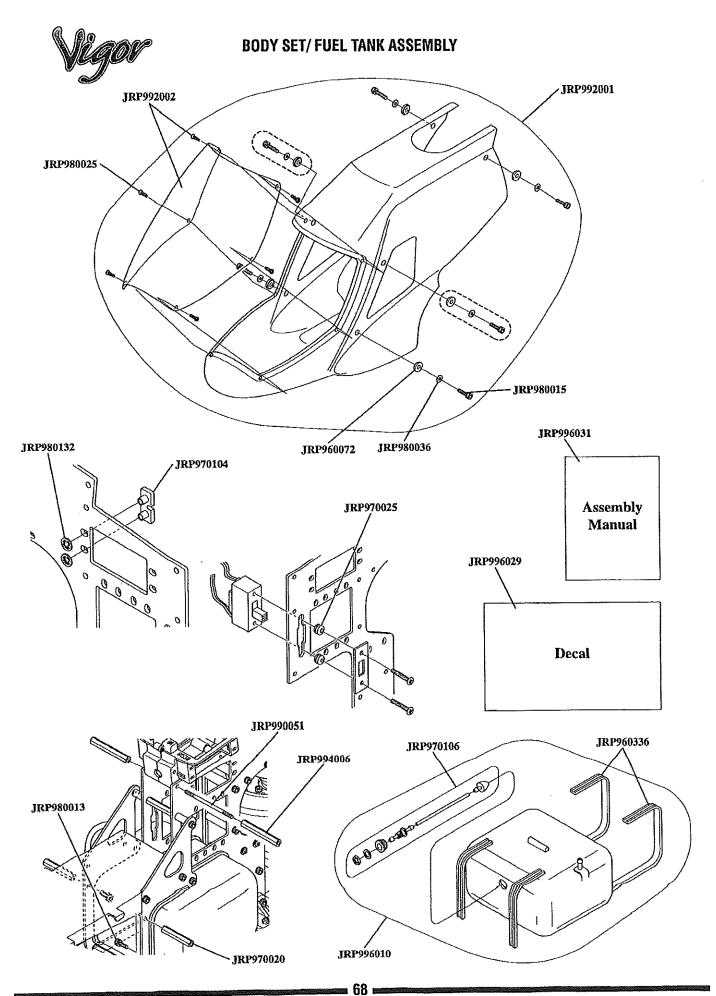
# VIGOR MANUAL PARTS LISTINGS Main Frame/Landing Gear/Autorotation assembly

	Paracipation	Quantity	Comments/ Additional Contents
Part #	Description		
980039	Nylon Lock Nut, 3mm Low Profile	10	
996009	Upper Main Shaft Bearing Block w/BB	1	Complete with Ball Bearing
994003	Tail Boom Mounting Clamp (Plastic)	1	
994009	Tail Boom Mounting Clamp (Aluminum)	1	Complete w/one 3.5x6 & one 3.5x8 Bolt
996004	I-Beam Crossmember "B"	2	
	Main Frame Set (Aluminum)	1	Complete Set (2pcs)
996019	Socket Head Bolt, 3x40mm	10	
980022	I-Beam Crossmember "A"	1	
996001	Main Frame Crossmember, 32mm	2	
970020 980061	Socket Head Bolt, 3x25mm	10	
980014	Socket Head Bolt, 3x10mm	10	
990053	Socket Head Bolt, 3.5x6mm	10	
970018	Mixing Lever Spacer	2	
980036	Flat Washer, 3mm	10	
980019	Socket Head Bolt, 3x22mm	10	
980122	Socket Head Bolt, 3x50mm	10	
9800122	Socket Head Bolt, 3x8mm	10	
970092	Main Frame Crossmember, 64mm	2	
970092	Spacer, 3x6x14mm	2	
970034	Spacer, 3x6x10mm	2 2 2	
996008	Fuel Tank Mounting Frames	2	
970204	Canopy Mounting Standoff		
960191	Front Radio Bed	1	
980004	Set Screw, 4x4mm	10	The Annual Cat Covers
970008	Main Shaft Collar	1	Complete w/four 4x4mm Set Screws
996012	Main Rotor Shaft	1	and Diagtic Concer
9960151	LSD Slipper Clutch Assembly	1	Complete w/Bolt, O-ring, and Plastic Spacer
994002	Autorotation Assembly Collar	1	Complete w/Bolt & Lock Nut
980018	Socket Head Bolt, 3x18mm Long Shank	, 5	
996005	Landing Strut Mounts	4	
980014	Socket Head Bolt, 3x10mm	10	
996018	Carbon Bottom Frame Plate	1	
980012	Socket Head Bolt, 3x6mm	10	
960338	Landing Struts, white	2	
980004	Set Screw, 4x4mm	10	
980060	Socket Head Bolt, 3x20mm	10	
960036	Antenna Tube	3	A Late withour Olde Cane
960119	Landing Skids	2	Complete w/four Skid Caps
970048	Landing Skid Caps	4	
996015	Autorotation Assembly	1	
996030	84T Molded Main Drive Gear	1	Complete w/one 6x10mm Hex Bolt
970047	Main Shaft Washer and Bolt	1	Polithisis avails ovioung usy page
994001	Steel Auto Hub Washer	1	•



### VIGOR MANUAL PARTS LISTINGS Tail Brace/ Tail Boom Assembly

Dovi #	Description	Quantity	Comments/ Additional Contents
Part #	Description	1	Complete w/Bolt
994004	Tail Brace Connector	2	Ompion moon
960047	Tail Brace Tube	5	Complete w/ail Hardware
996024	Tail Rod Guide Set	1	Complete w/all Hardware
996022	Horizontal Fin/Brace Clamp		1- Vertical and 1- Horizontal Fin w/Hardware
960197	Tail Fin Set	1	1- Action and 1 Houseway in a
970020	Main Frame Standoff , 32mm	2	
980009	Socket Head Bolt, 2.6x12mm	10	
980014	Socket Head Bolt, 3x10mm	10	•
980016	Socket Head Bolt, 3x15mm	10	
980024	Self Tapping Screw, 2x8mm	10	
980036	Flat Washer, 3mm	10	
980070	Nylon Lock Nut, 3mm	10	
980084	Set Screw, 3x30mm	5	
980088	Dome Nut, 3mm	10	2 Brace Tubes, 4 Brace Connectors and Hardware
993003	Tail Brace Set	1	2 Brace Tubes, 4 Brace confinences and transfer
983044	Tail Control Rod	1	
993002	Tail Boom	1	OIsta witten Overme Corouse
970002	Steel Joint Ball w/ 2x10mm Screw	10	Complete w/ten 2x8mm Screws
960128	Tail Blade Holder Set	1	1 Complete Set (4pcs)
976103	O-Ring, Tail Hub	2	
980131	Socket Head Bolt, 2x10mm	10	
981034	Thrust Bearing, 4x9x4mm	2	
981018	Open Bearing, 4x10x4mm	2	
960129	Tail Rotor Blades	2	
970054	Washer, 4x7x0.5mm	2	
970065	Washer, 7x10x1mm	2	
981019	Sealed Bearing, 4x10x4mm	2	
980128	Nylon Lock Nut, 2mm	10	Ourselete ma pagemblad
960050	Tall Slide Ring Assembly	1	Complete, pre-assembled
980067	Set Screw, 3x3mm	0	Complete w/two Pins
960056	Tail Pitch Link	2	Combiers witho Line
960057	Tail Pitch Plate	1	Complete w/Bearing
960058	Tail Slide Ring	1	Complete Mipeguing
970028	Tail Slide Ring Sleeve	1	
981004	Bearing, 5x13x4mm	2	Complete w/Spring Pin
970027	Tail Output Shaft	1	Complete Mobiling i in
960188	Tail Drive Belt	- <u>1</u>	
980078	Spring Pin, 2x13mm	5	Olake well-nying Pin
960187	Tail Case Pulley	1	Complete w/Spring Pin 1-Left, 1 Right Half Complete w/Hardware
996023	Tail Case Set, Black	1	Complete w/ten 2x8mm Screws
970001	Steel Joint Ball w/2x8mm Screw	10	Complete witer 2xouth octows
980129	Nylon Lock Nut, 2.6mm	10	
980089	Socket Head Bolt, 2.6x10mm	10	Complete w/ali Hardware
996025	Tail Pitch Control Lever, w/Steel Sleev	e 1	Collibiate Man Haroward
980034	Flat Washer, 2mm	ΙŲ	
980008	Socket Head Bolt, 2x20mm	10	
970004	Universal Ball Link	10	·
970018	Mixing Lever Spacer	2	
980019	Socket Head Bolt, 3x22mm	10	Complete Assembly
960470	Tail Botor Hub Assembly, Complete	1	Complete Assembly 1 Complete set (4pcs) with Hardware
960507	Tail Blade Holder Set w/Hardware	1	Complete w/two O-Rings
960370	- a serie i i i i i i i i i i i i i i i i i i	1	Combiers Avian ourman



### VIGOR MANUAL PARTS LISTINGS Body Set/ Fuel Tank Assembly

Part #	Description	Quantity	Comments/ Additional Contents
992002 992001 980025 960072 980036 980015 980132 970104 970025 990051 994006 980013 970020 970106 996010 960336 996031 996029	Vigor Canopy Lens Vigor Body Set Self Tapping Screw, 2.6x8mm Rubber Body Grommets Flat Washer, 3mm Socket Head Bolt, 3x12mm CA Stopper Ring, 3.5mm Servo Mounting Plates, Type B Switch Mounting Grommets Threaded Rod, 3x50mm Main Frame Standoff, 41mm Socket Head Bolt, 3x8mm Main Frame Standoff, 32mm Fuel Tank Hardware Set Vigor Fuel Tank Set Tank Mounting Rubber (3 ft) Vigor Instruction Manual	1 10 4 10 10 10 10 4 2 2 10 2 1 1 1	Complete w/Canopy Lens and Screws  Complete with Stopper, Clunk, Nut, and Washer Complete with all Tank Hardware



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